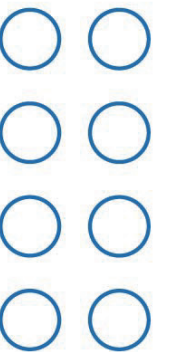
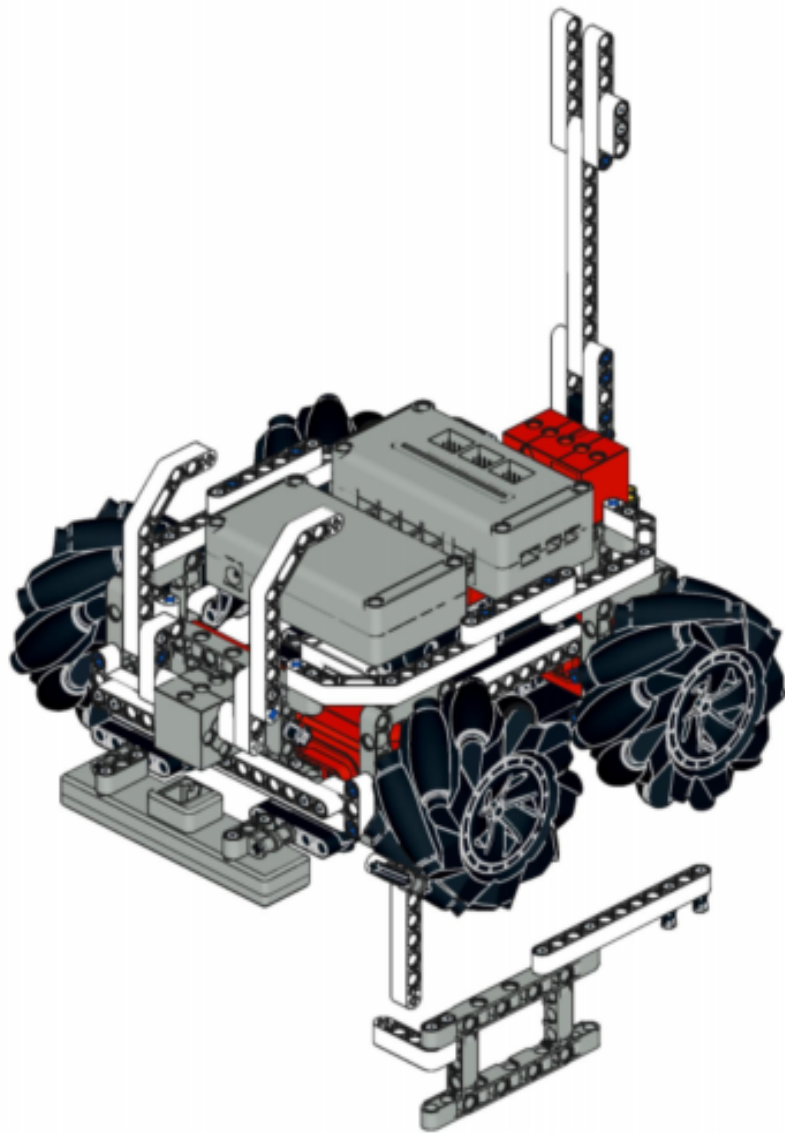
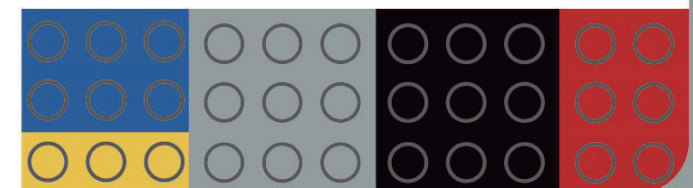
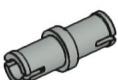


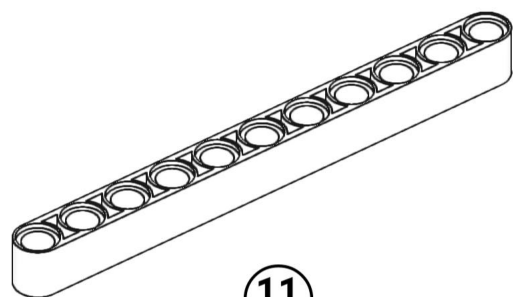
AISTEAM 205S Robot Car



Building Guide

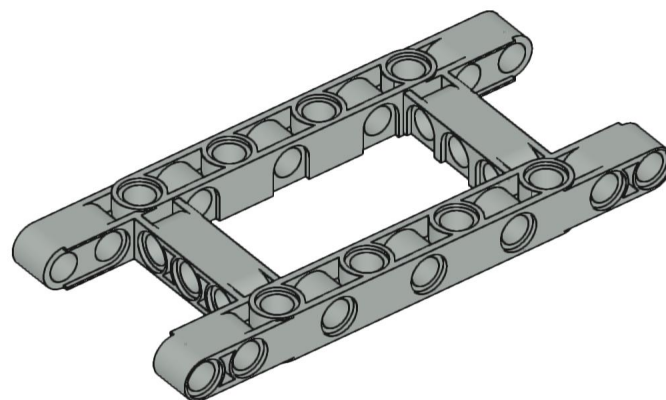



3x
8x
1x
80x
10x
6x
2x
1x
2x
1x ③
1x 3#
2x
1x
22x
2x
2x
1x 4#
4x
2x
5x
2x ⑤
5x ⑦
1x
4x
6x

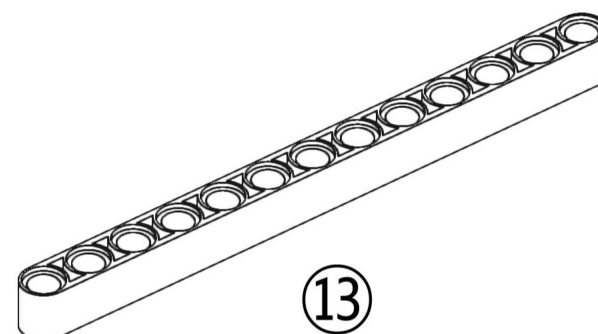


3x

⑪

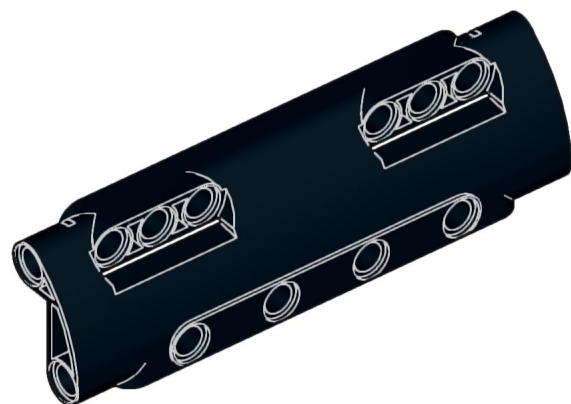


4x

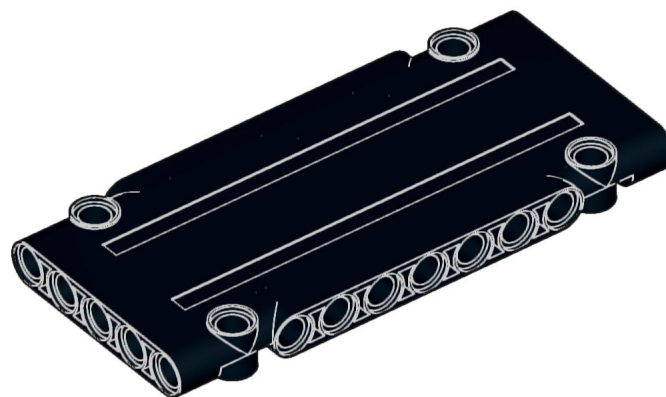


1x

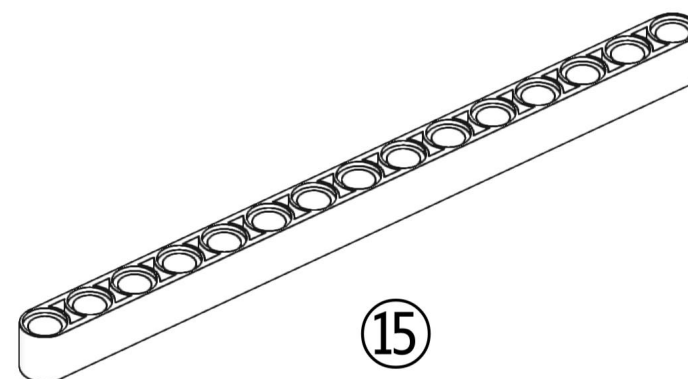
⑬



2x

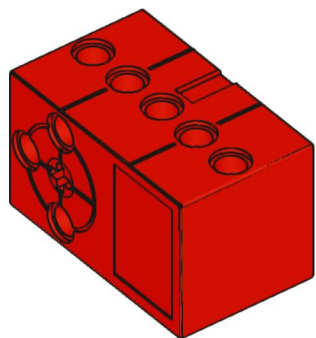


4x

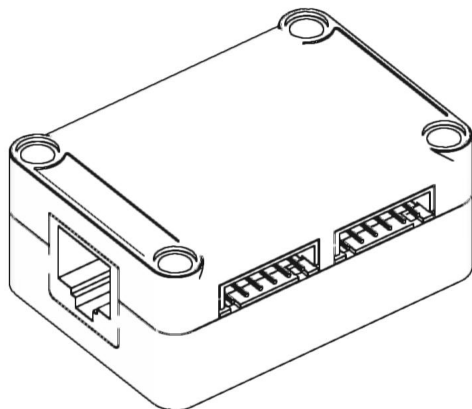


4x

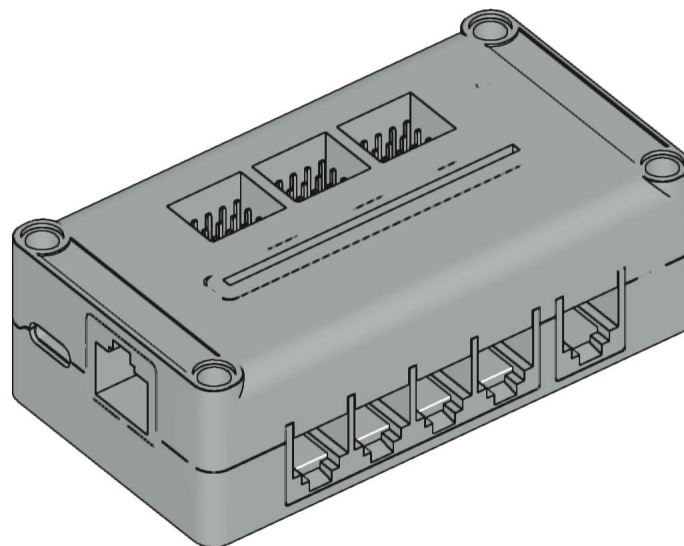
⑮



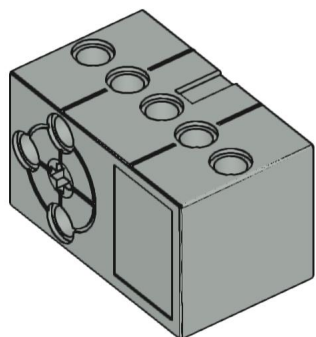
1x



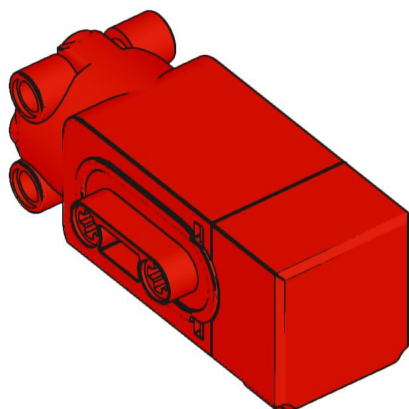
1x



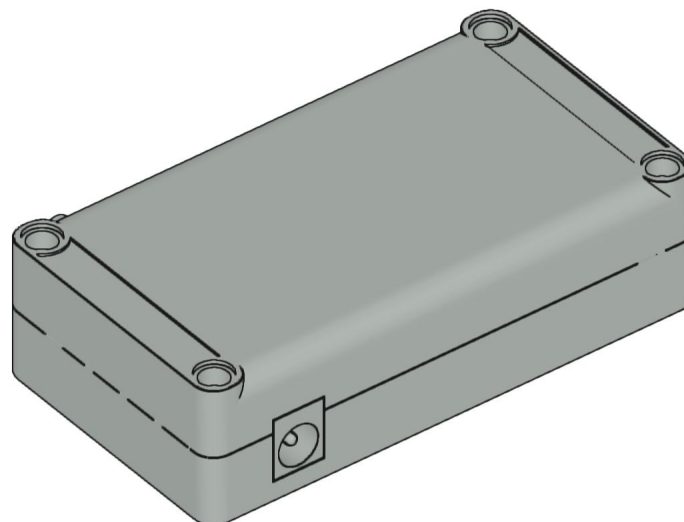
1x



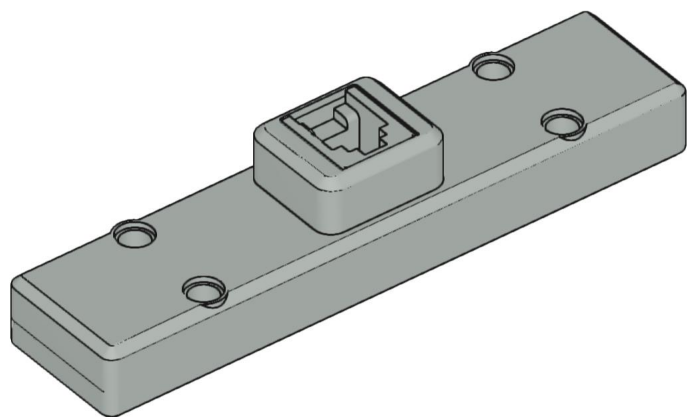
1x



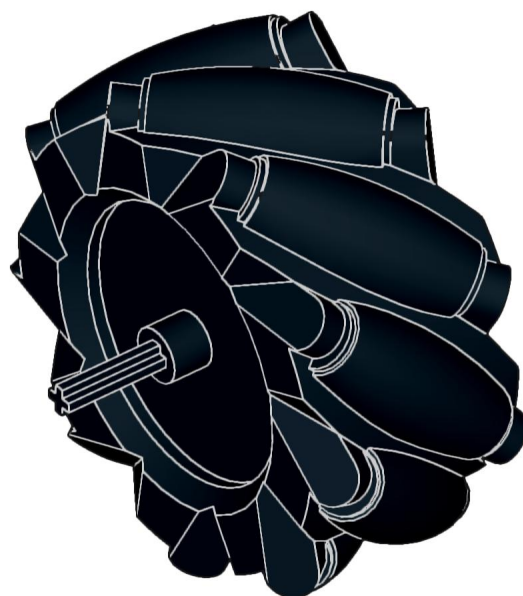
4x



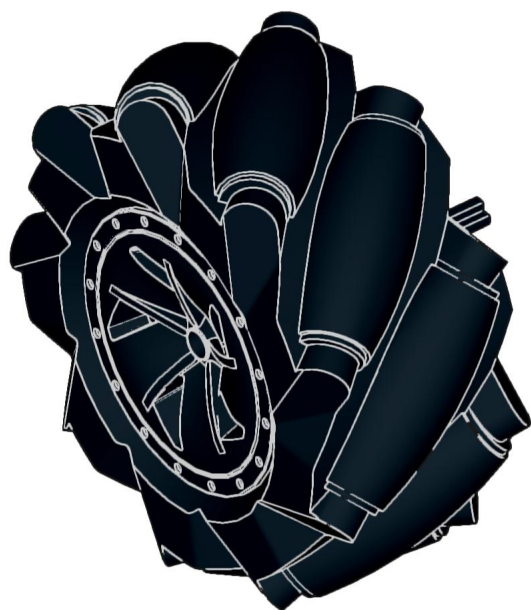
1x



1x

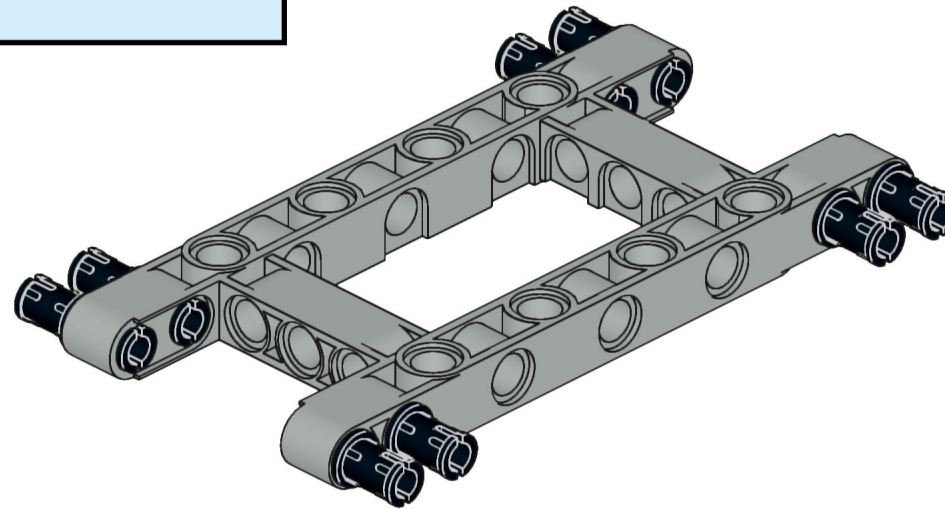
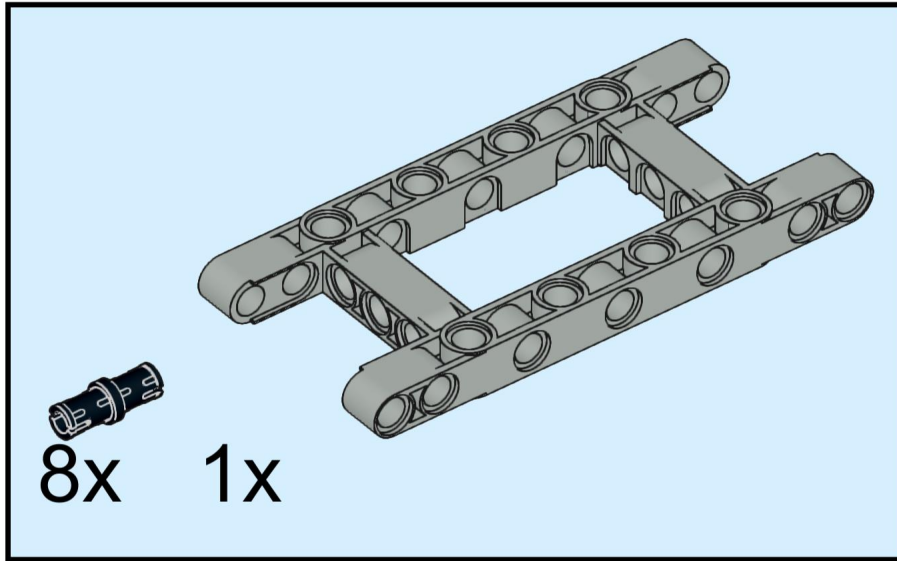


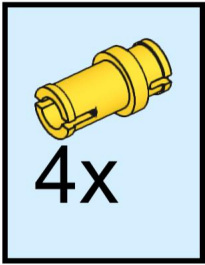
2x



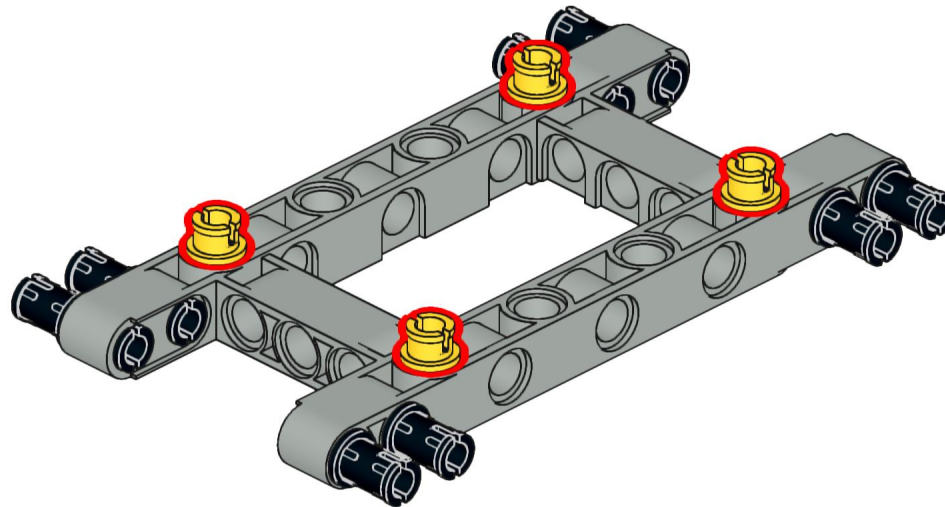
2x

1

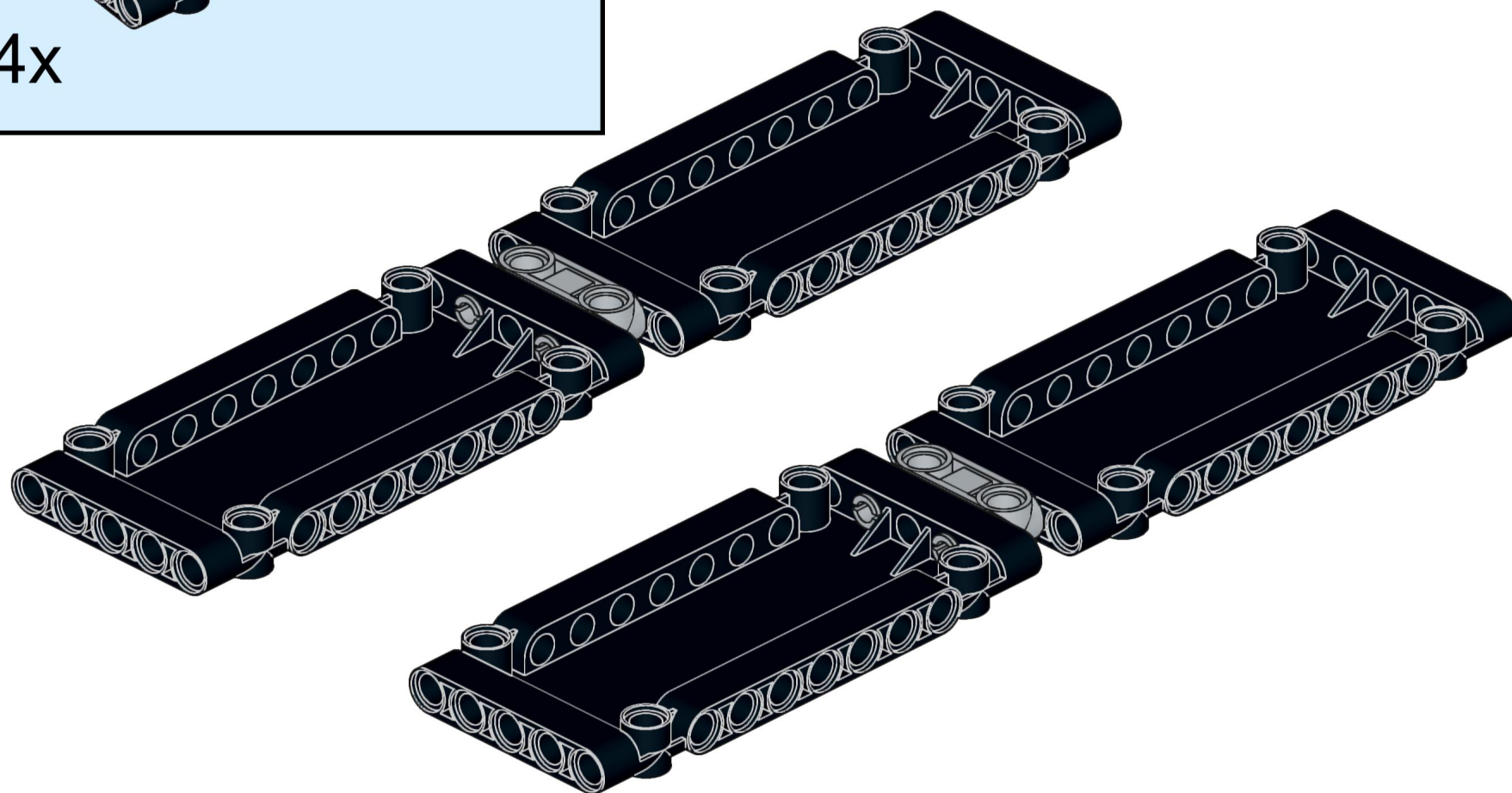
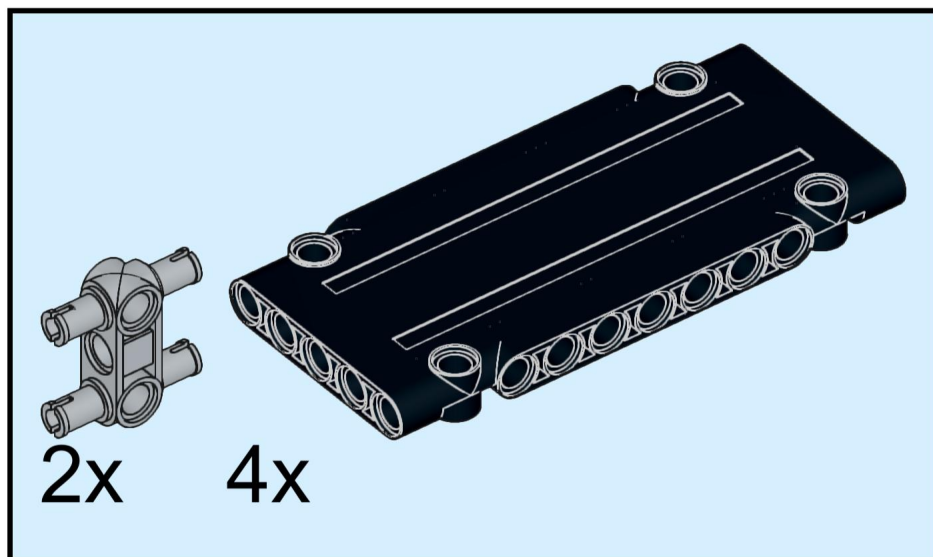




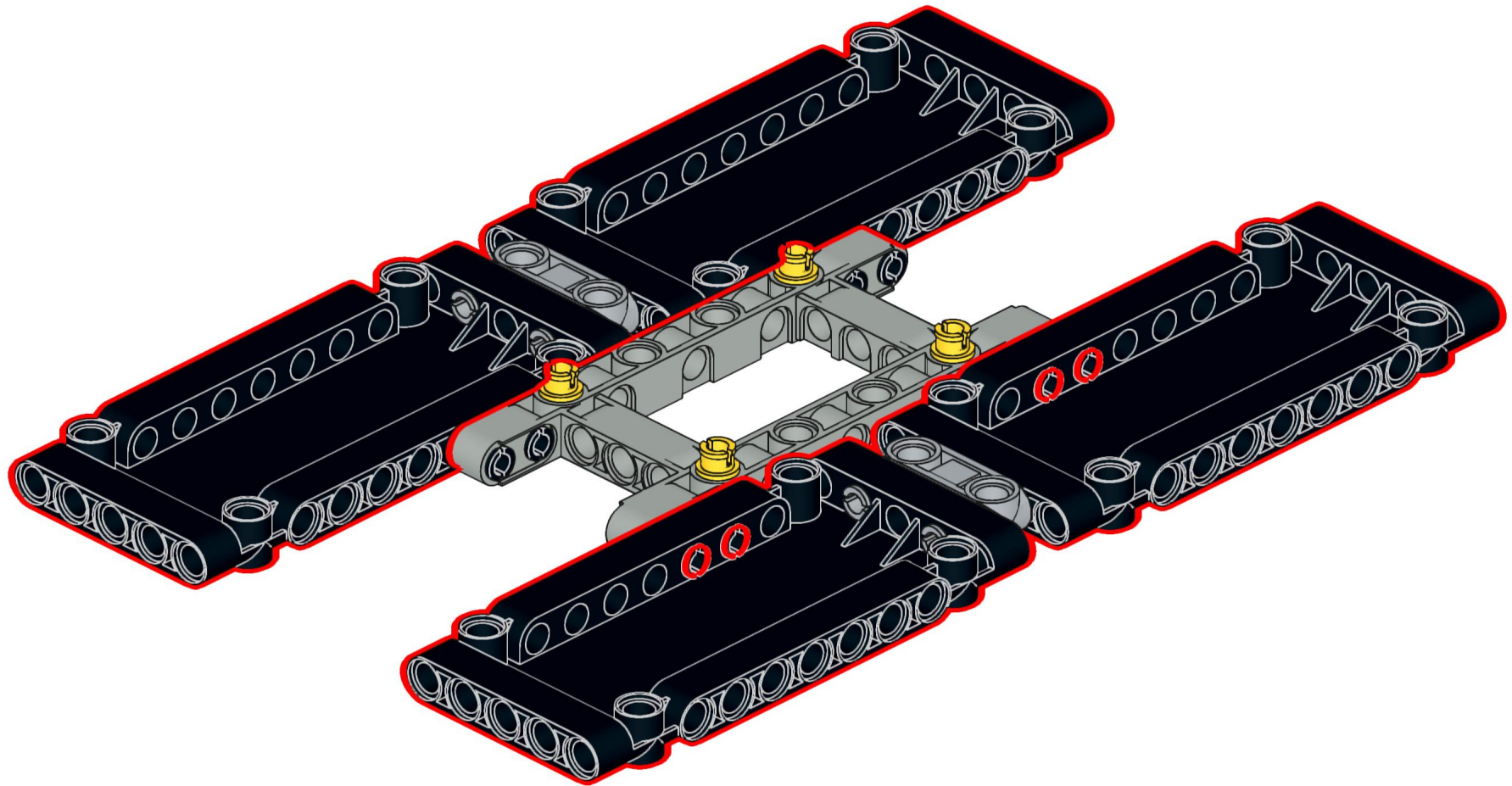
2

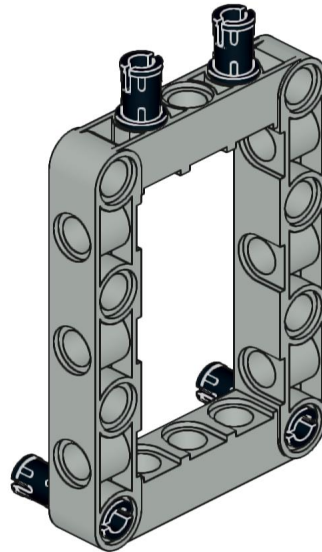
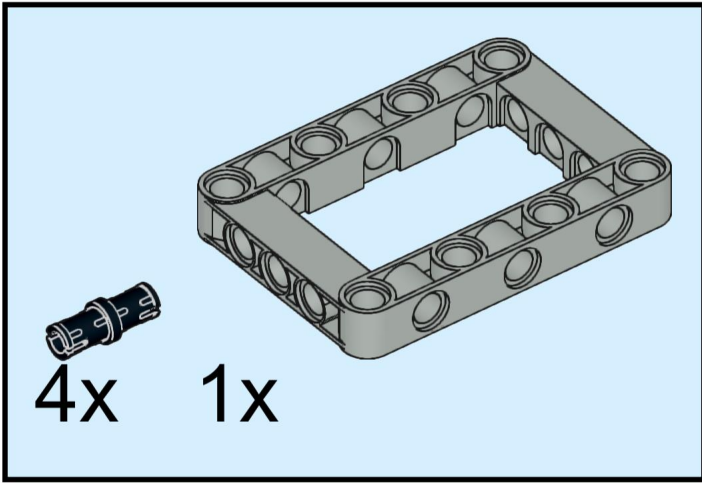


3

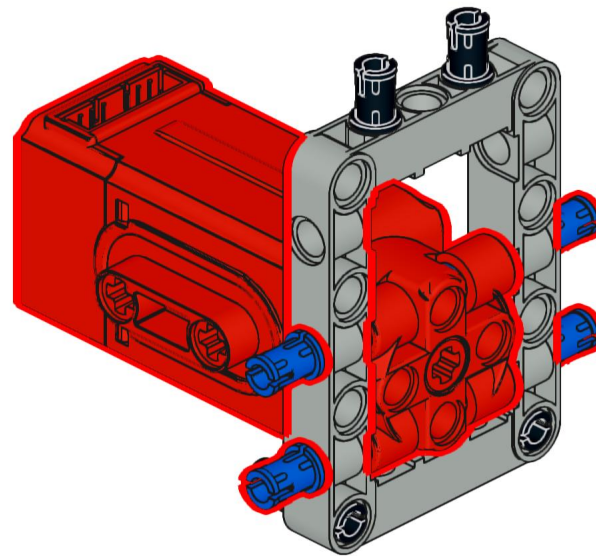
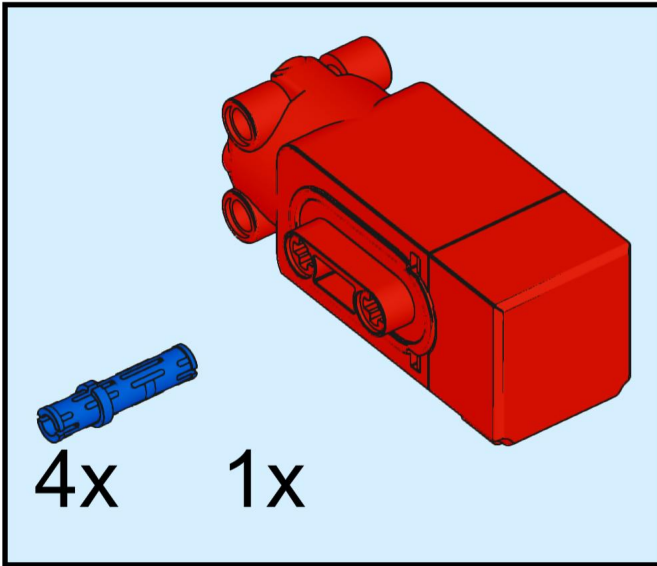


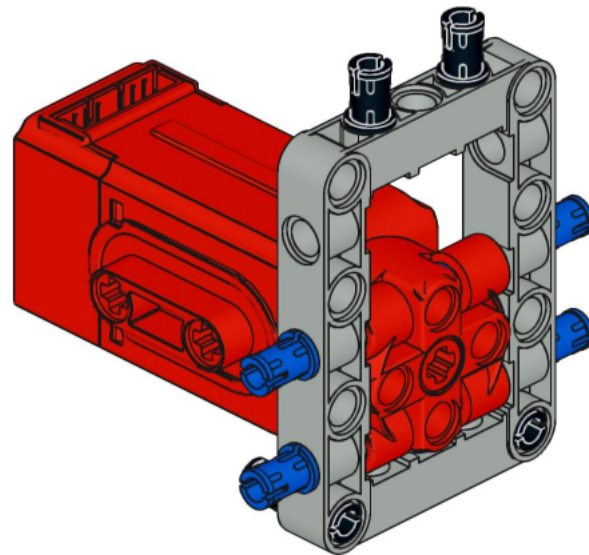
4



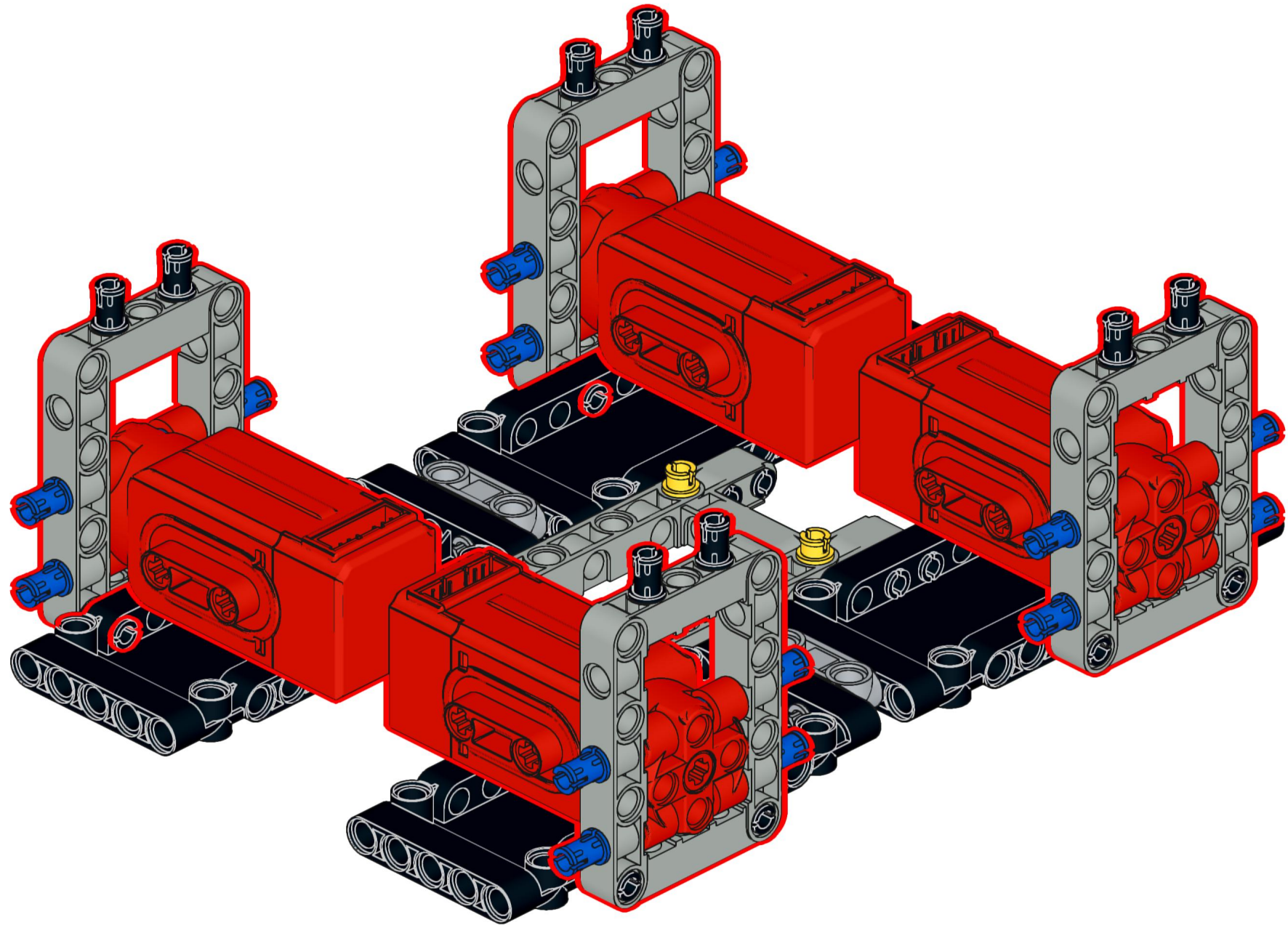


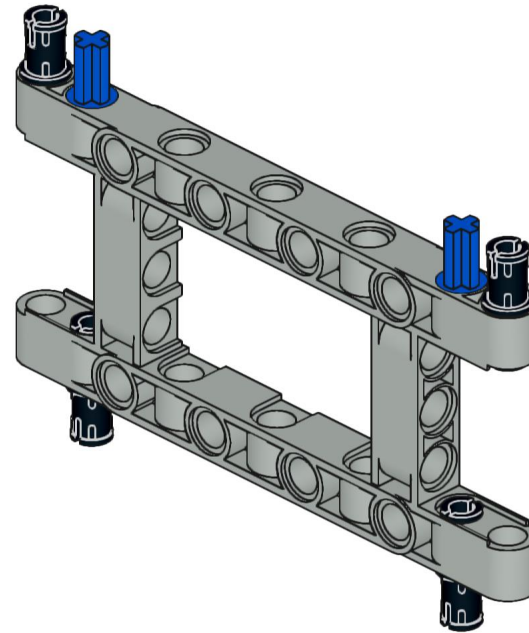
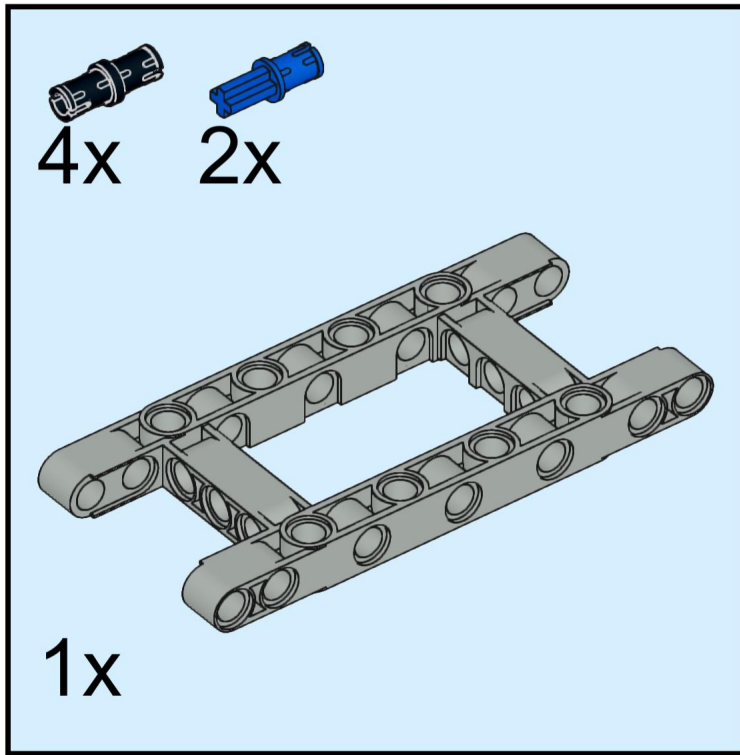
6



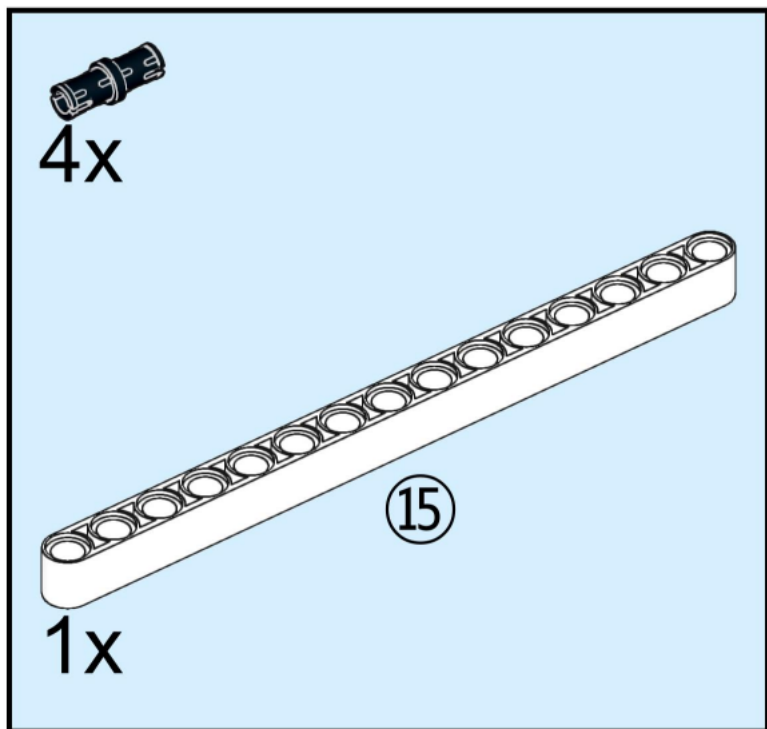


X 4

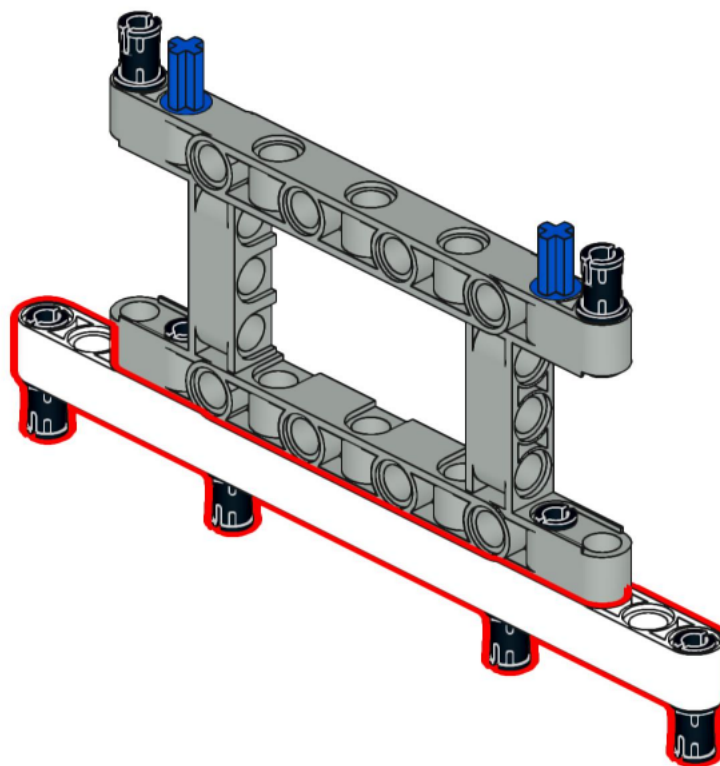


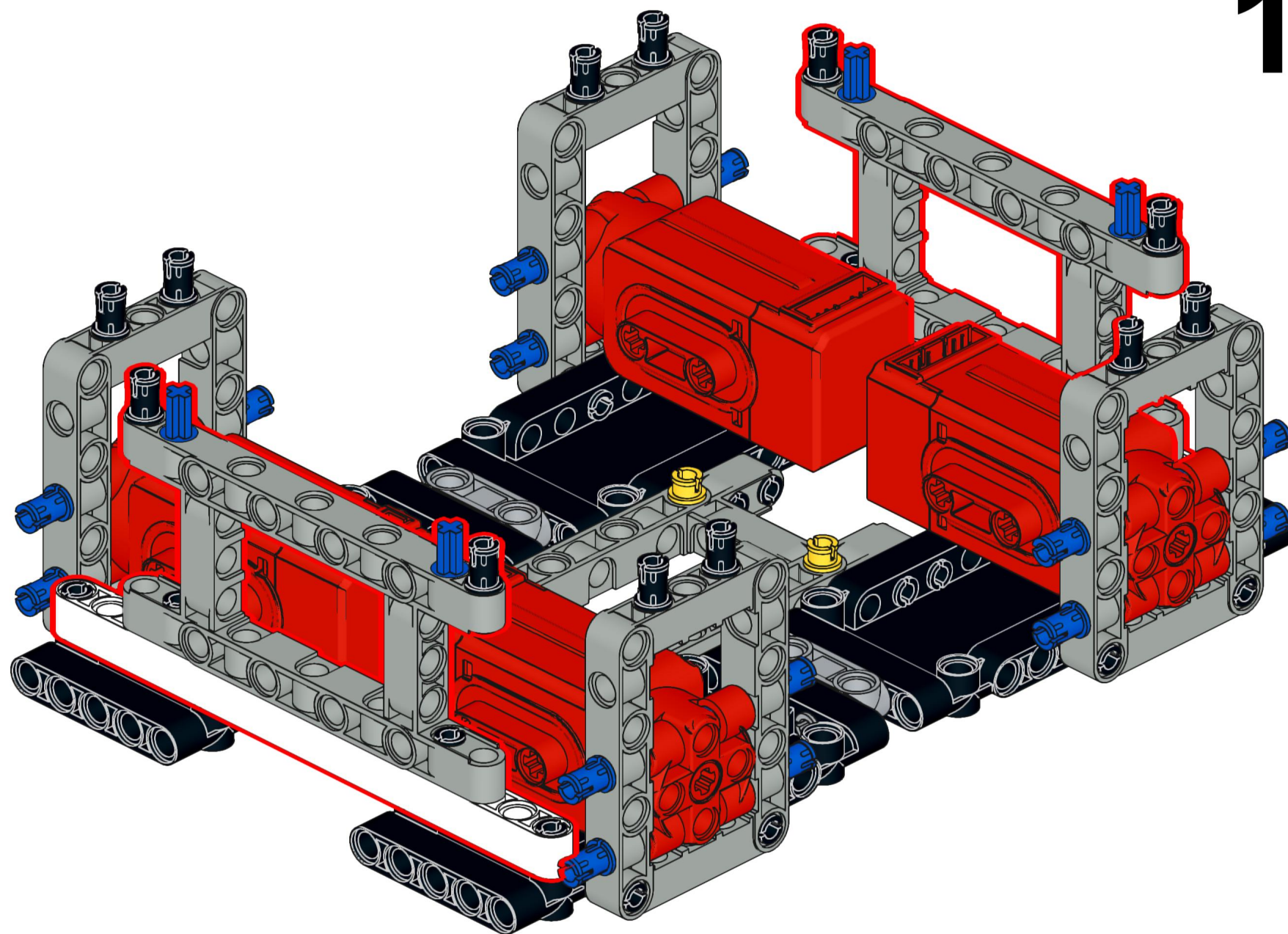


10

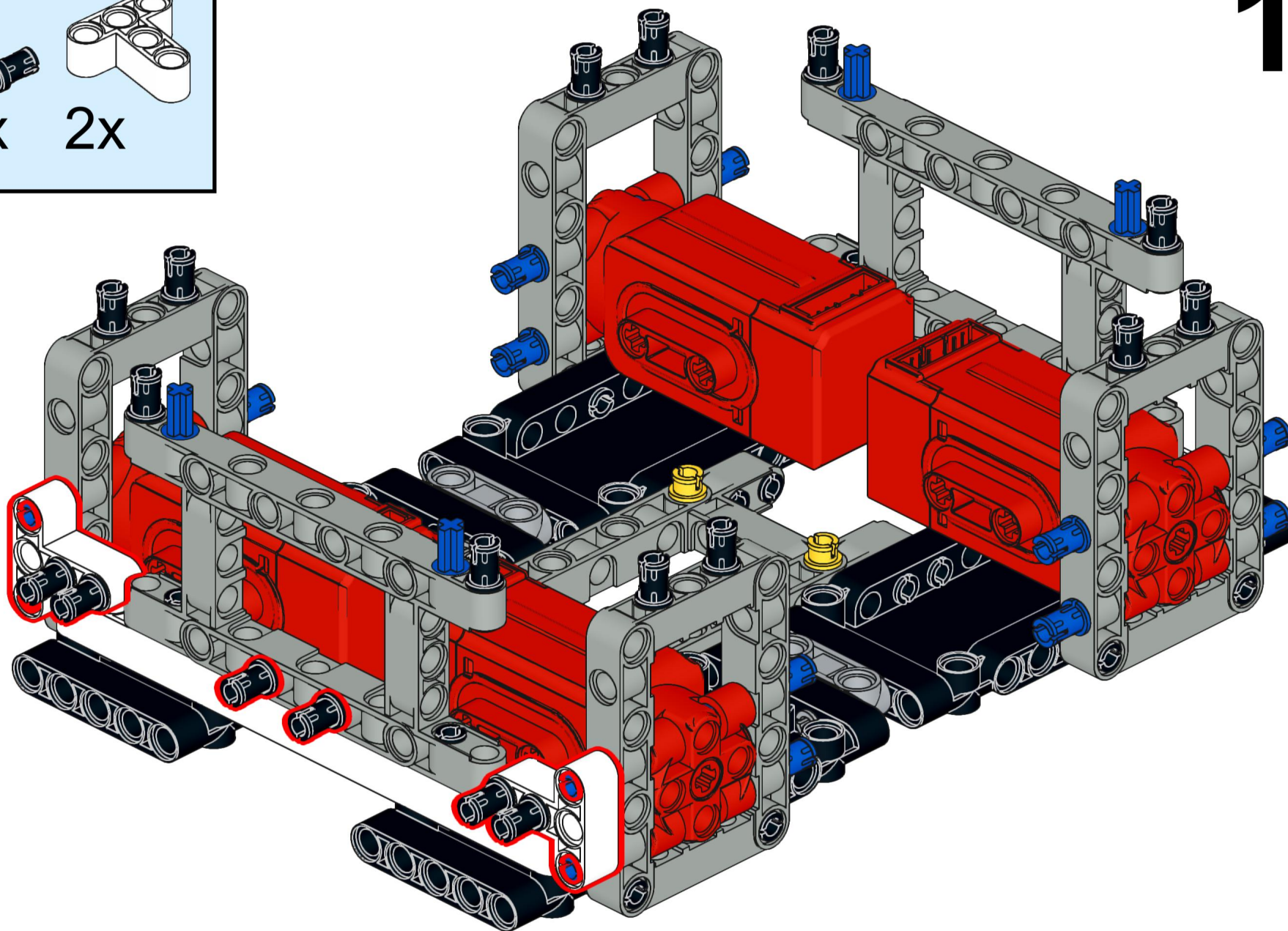
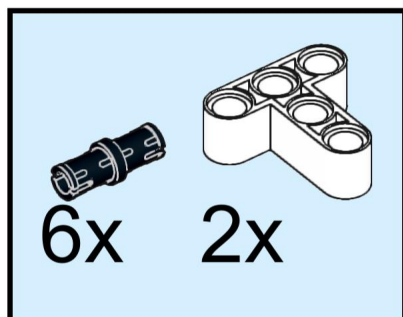


X 2

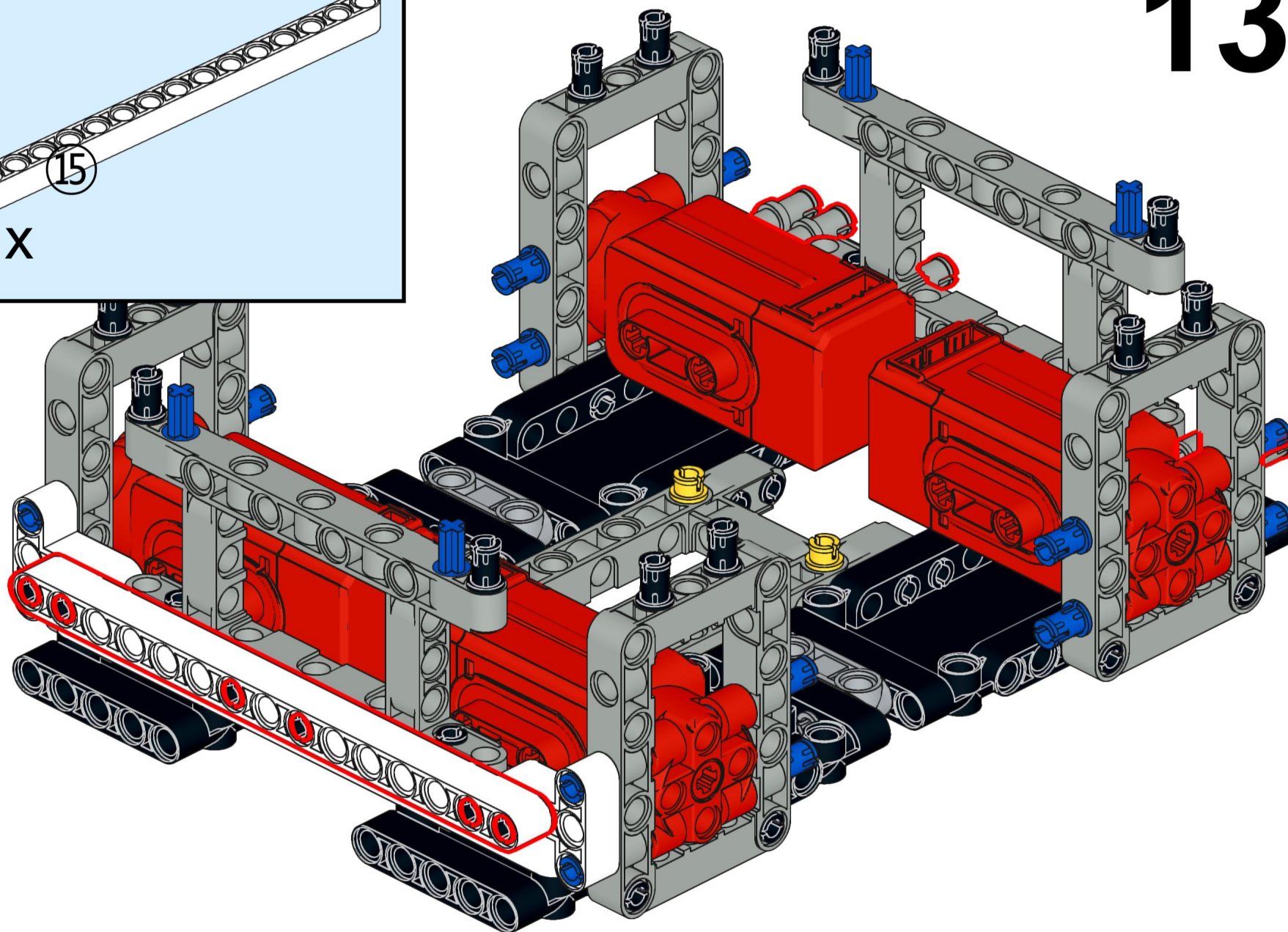
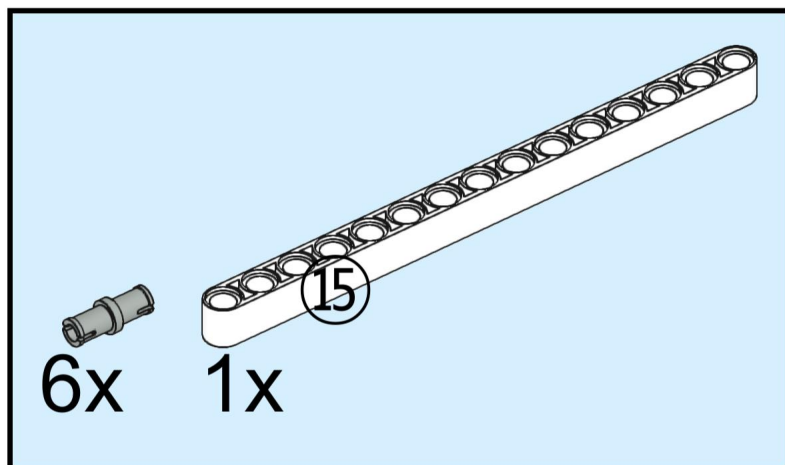




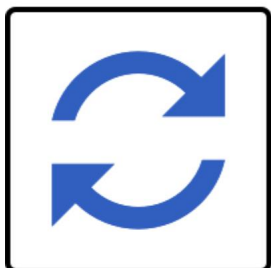
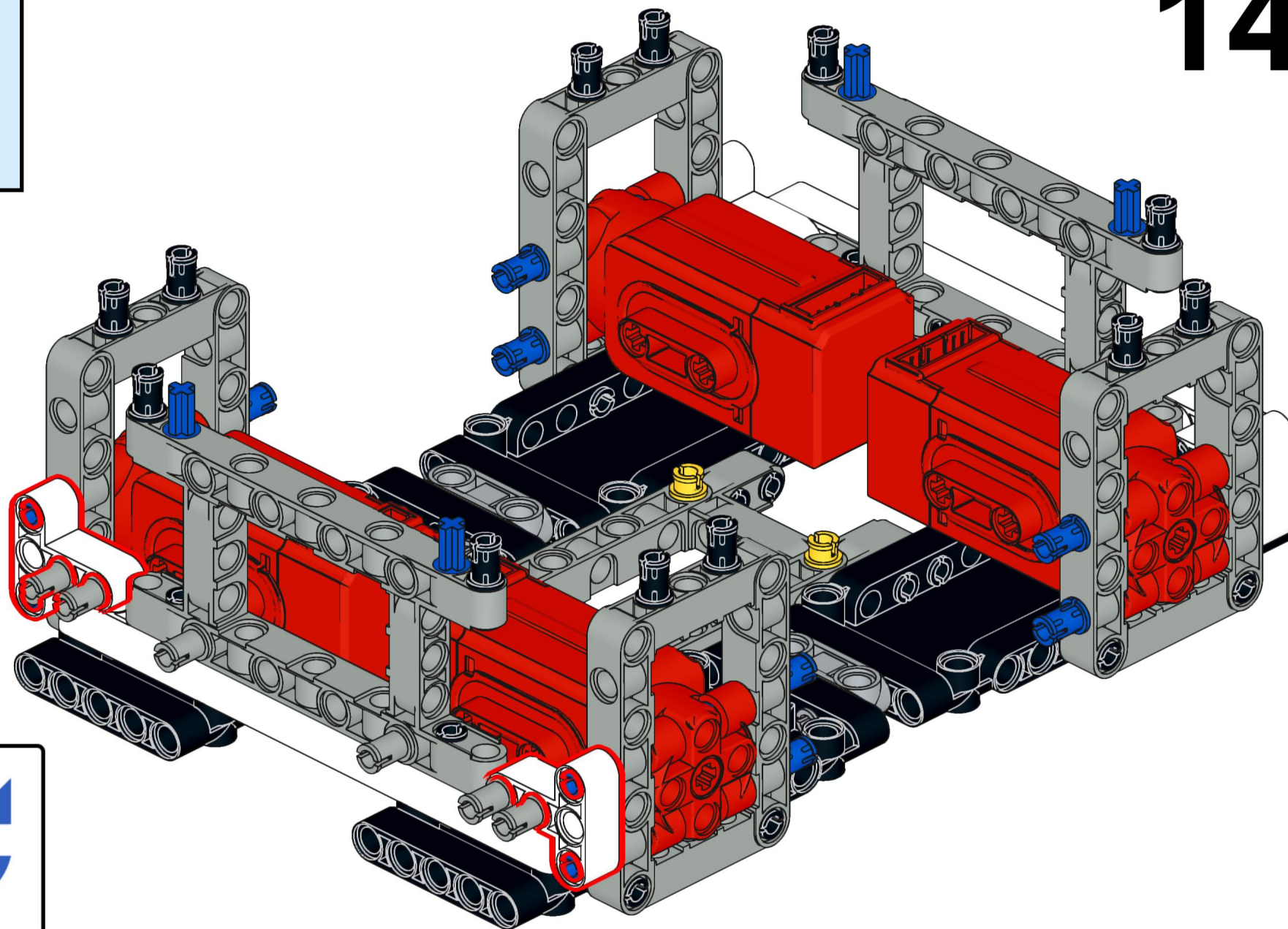
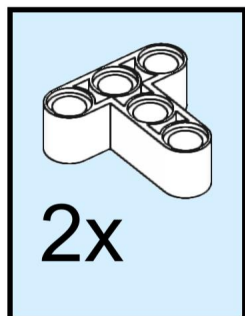
12



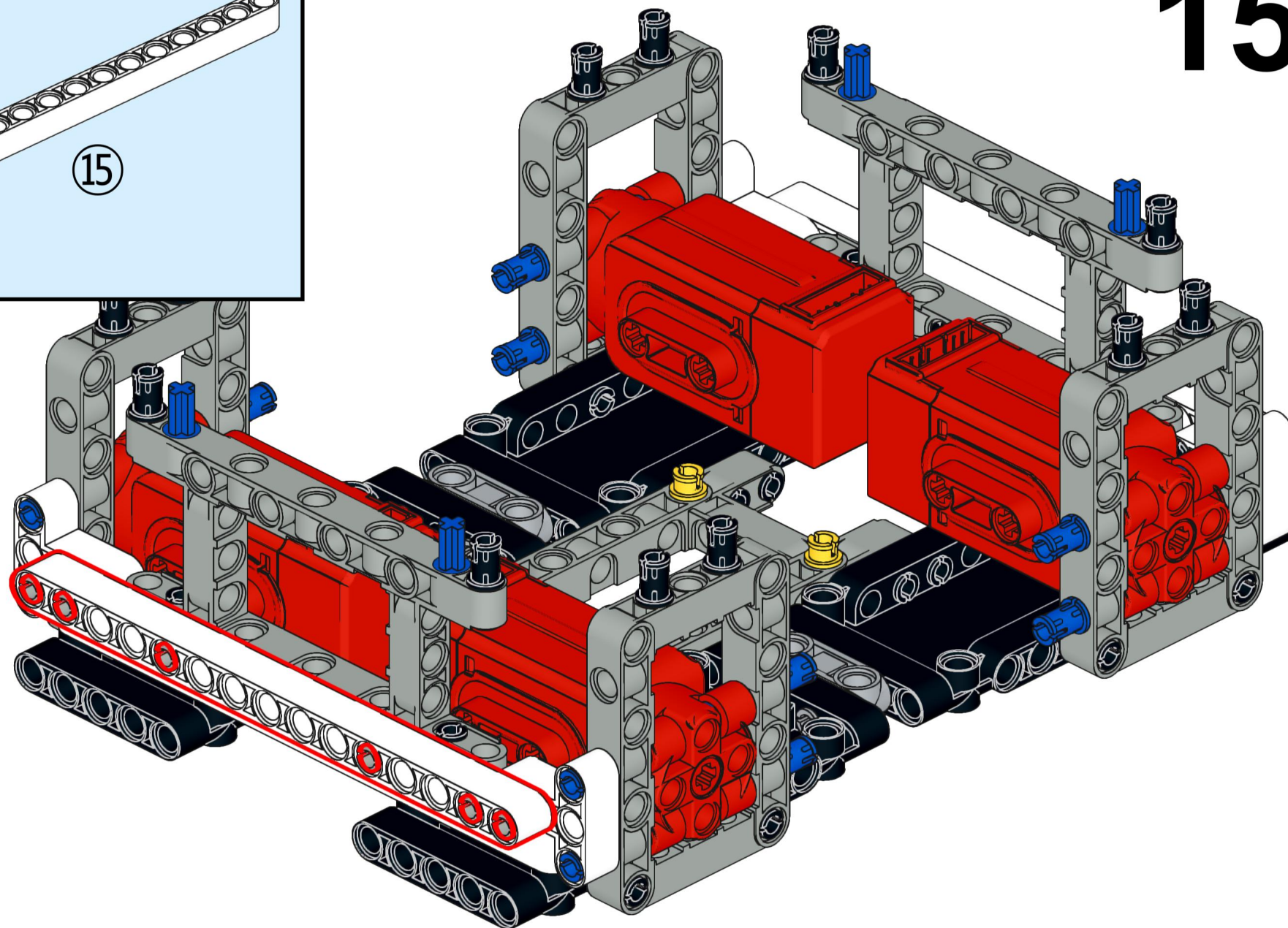
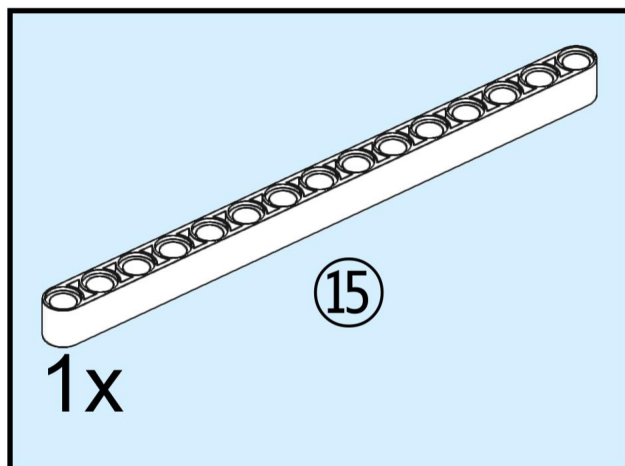
13



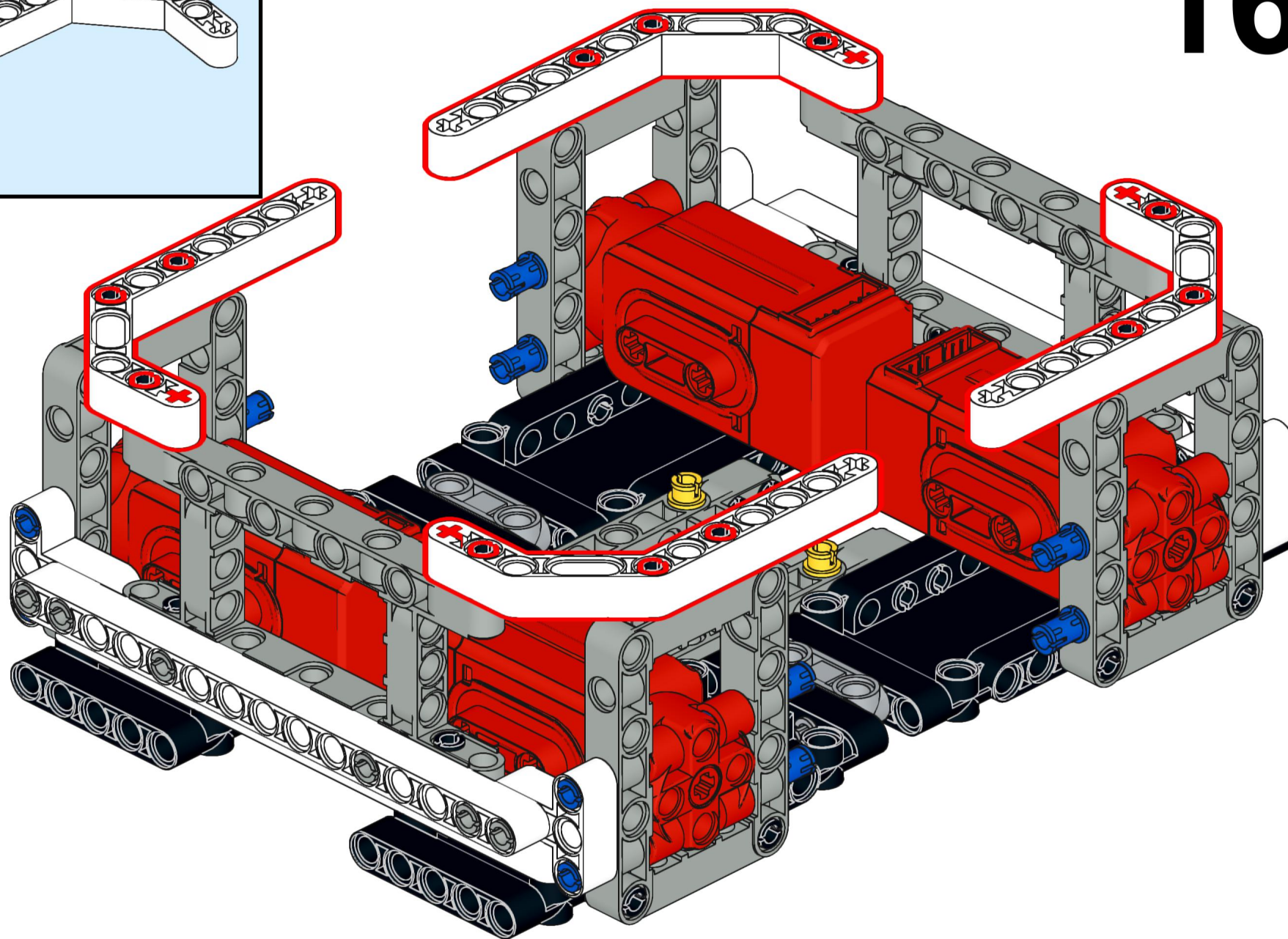
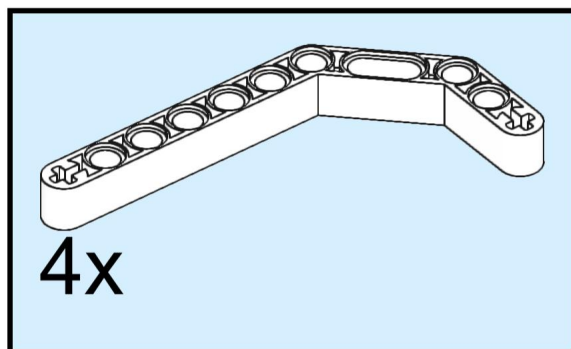
14



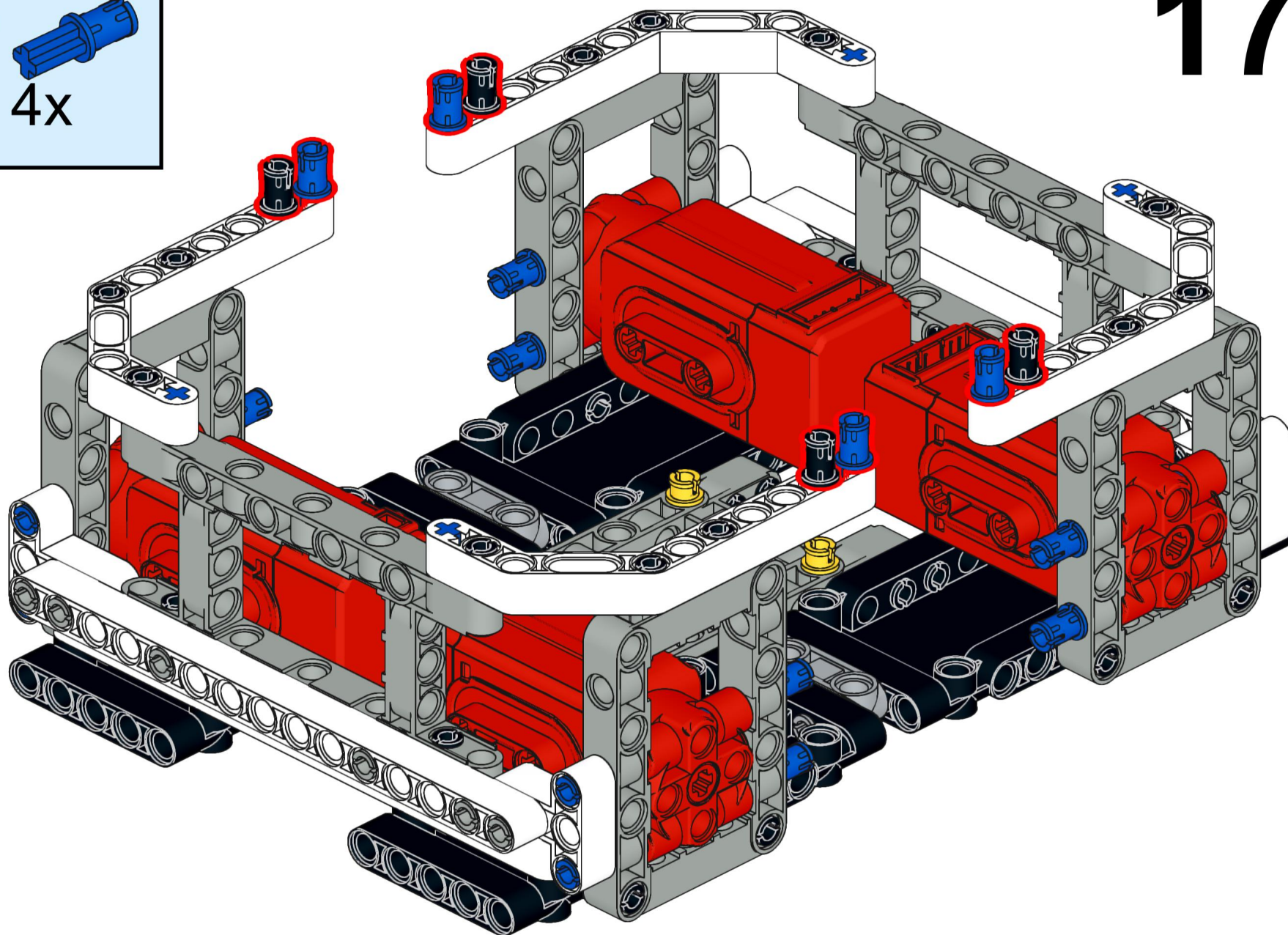
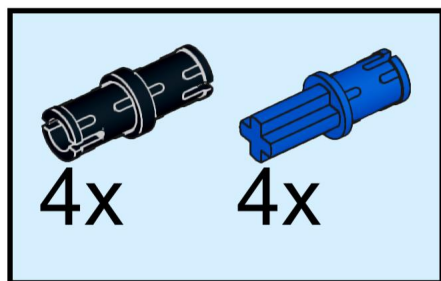
15



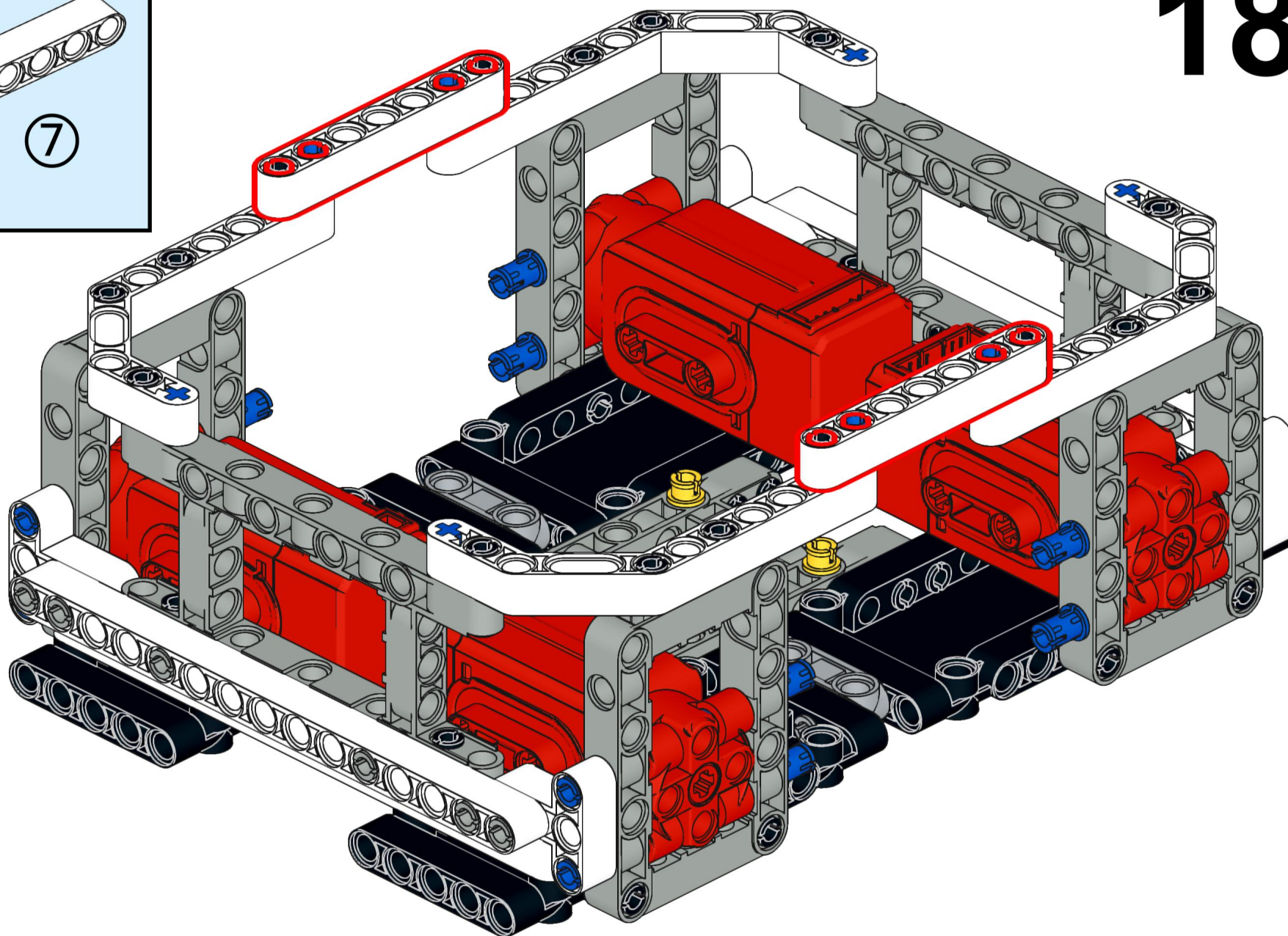
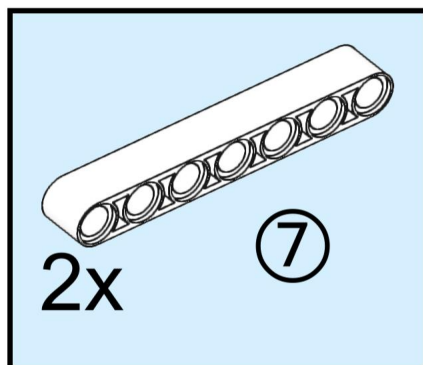
16

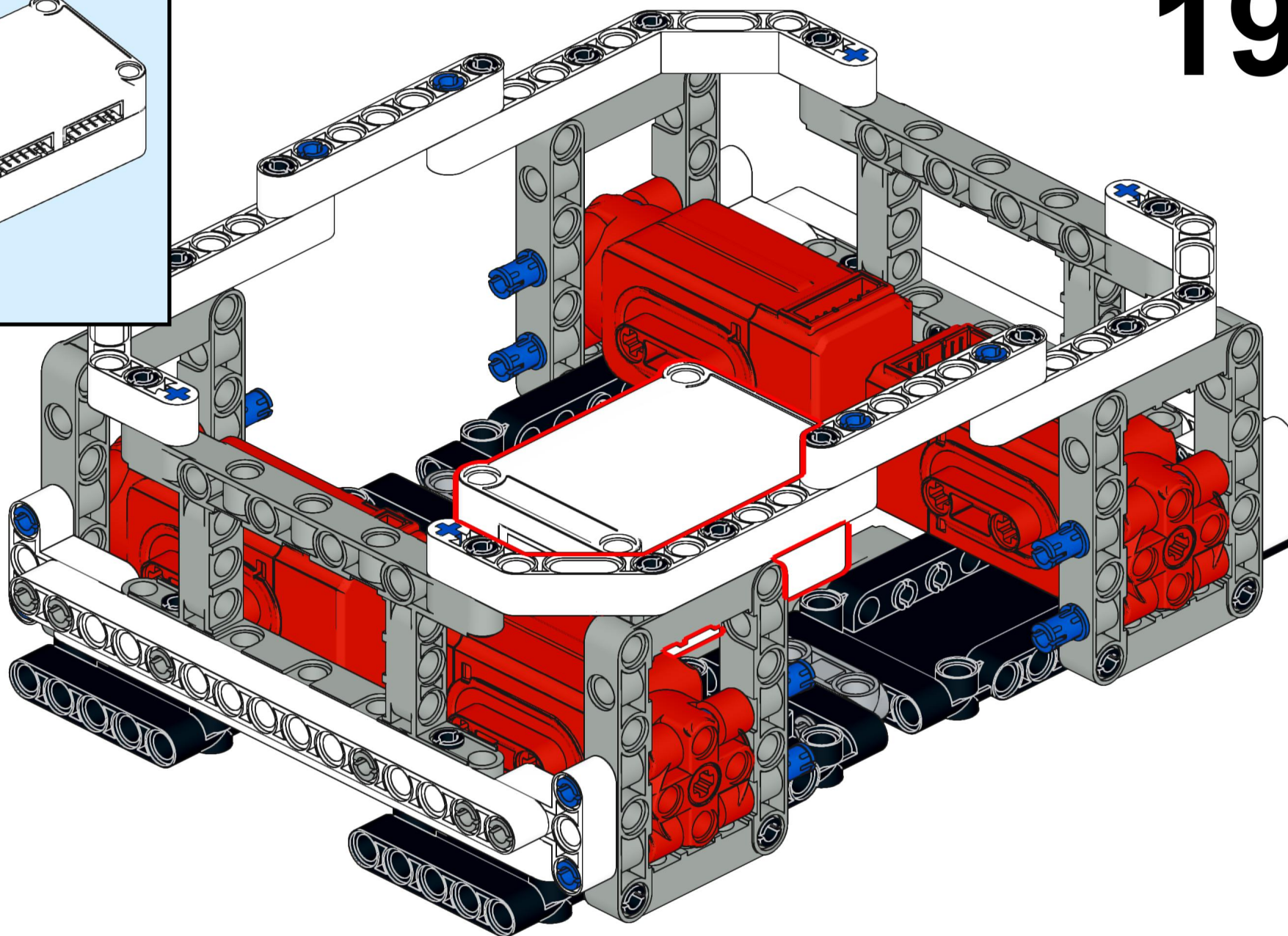
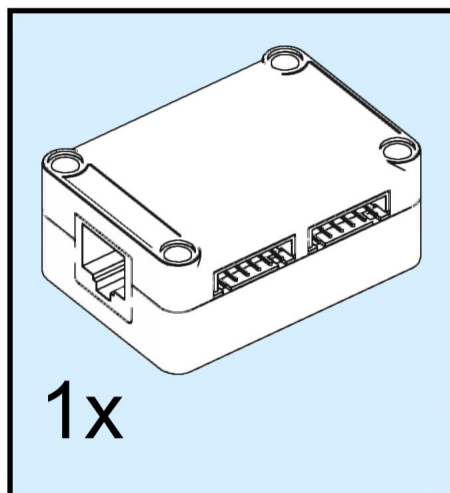


17

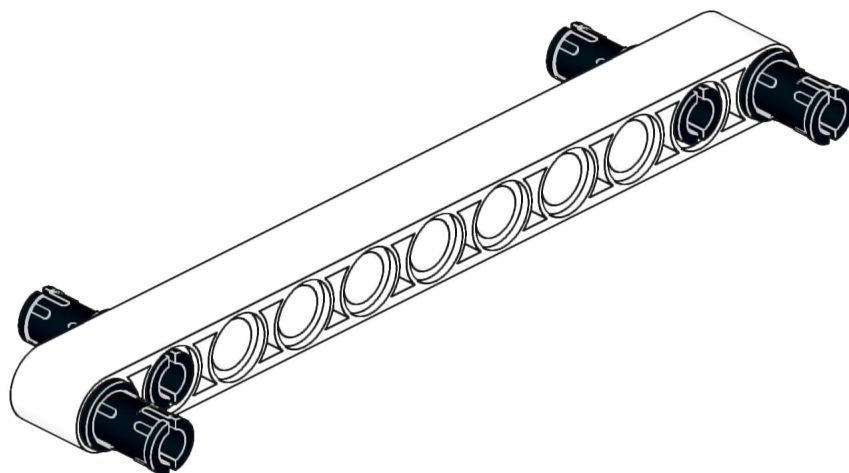
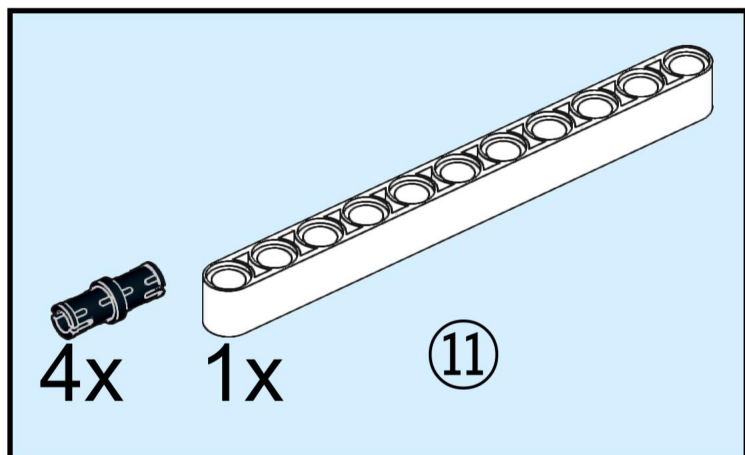


18

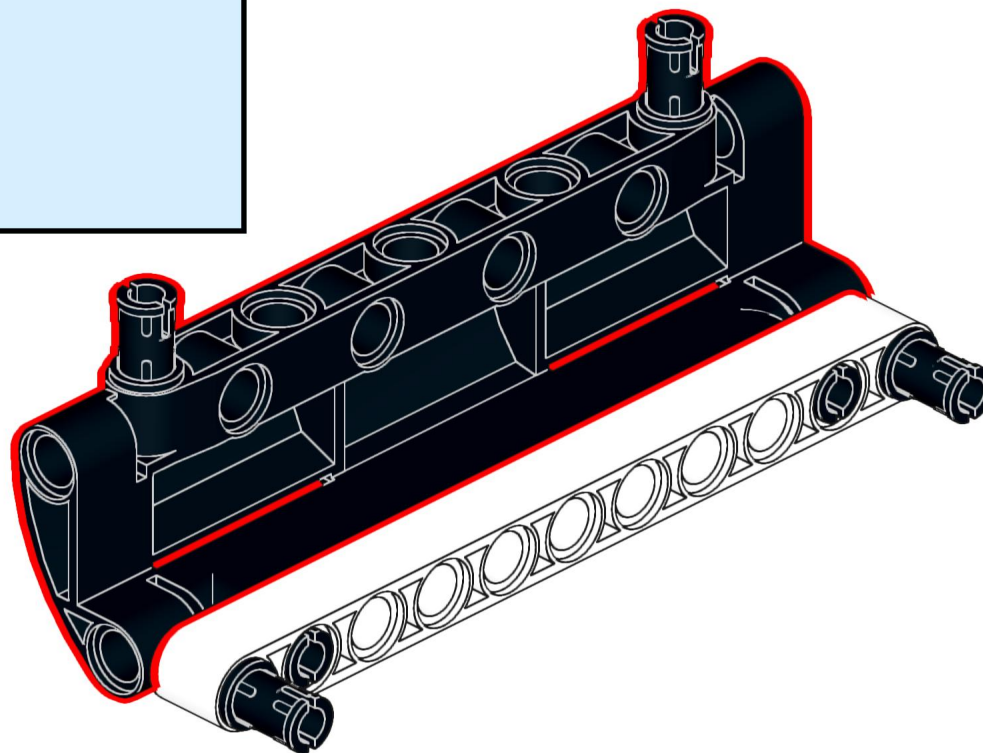
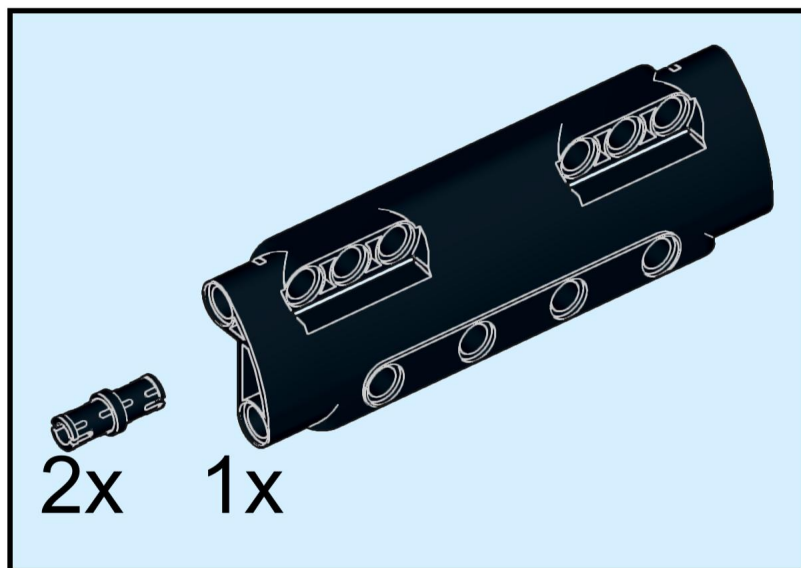




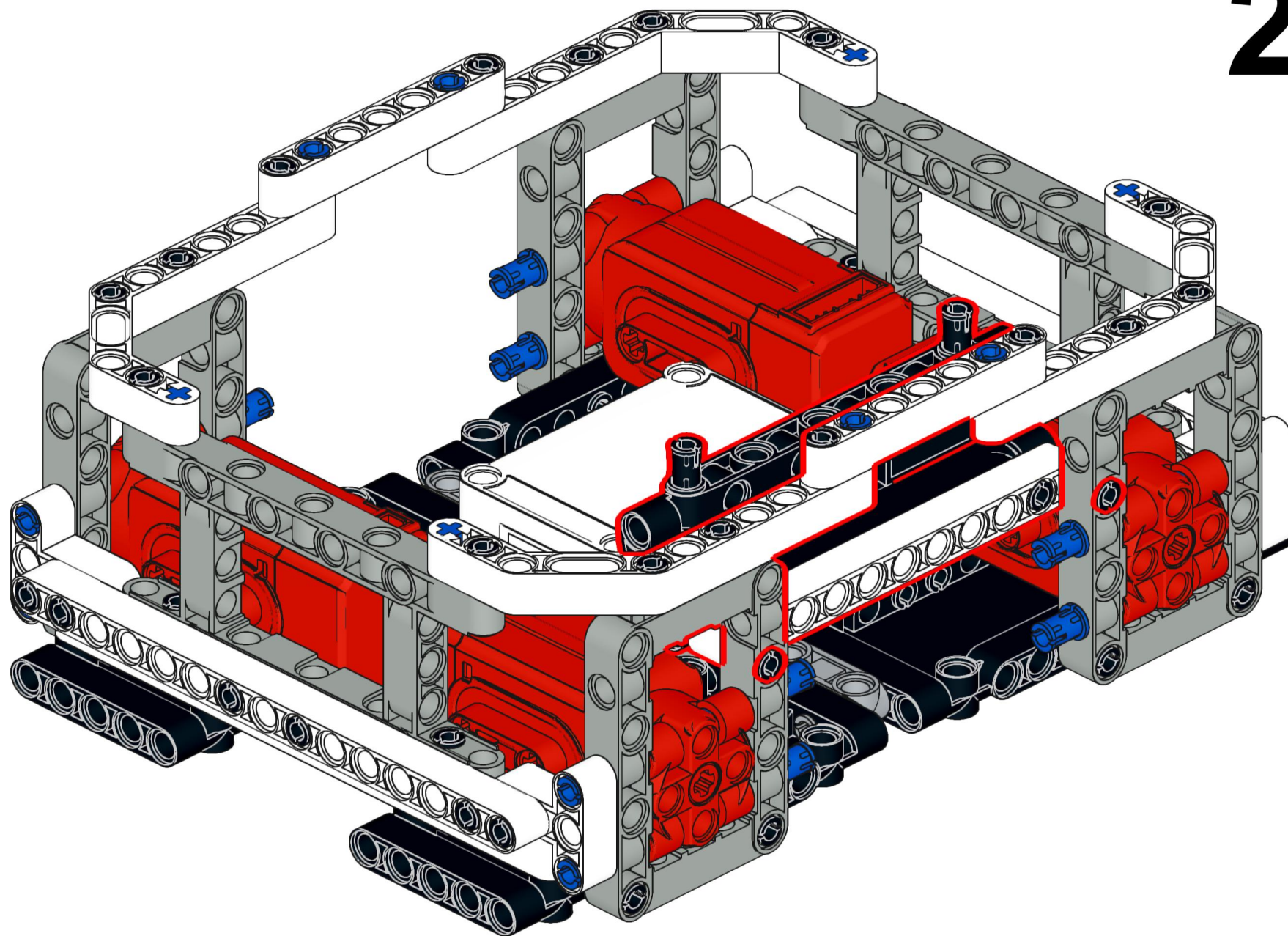
20

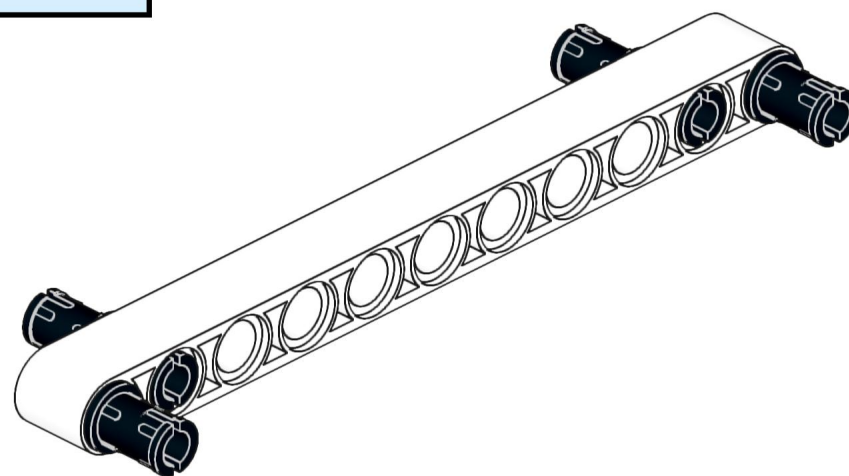
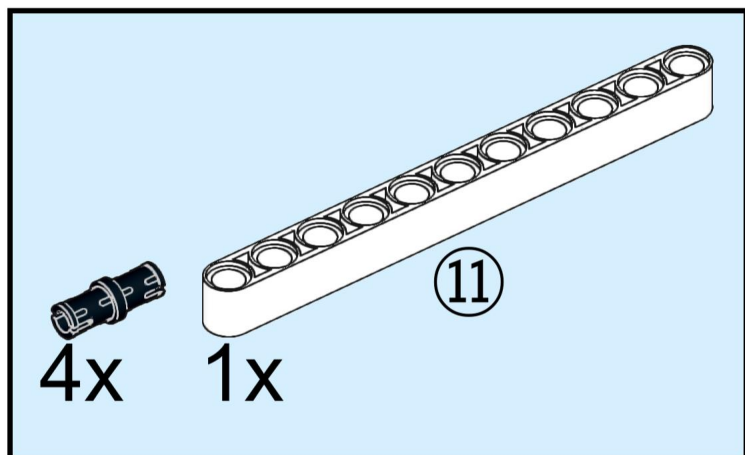


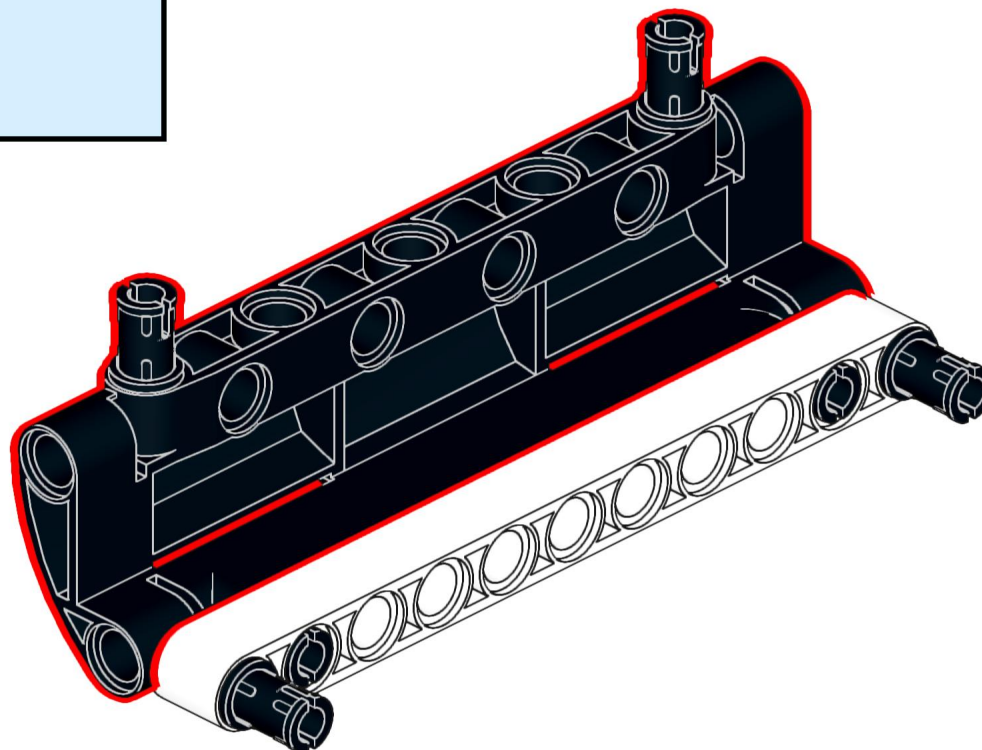
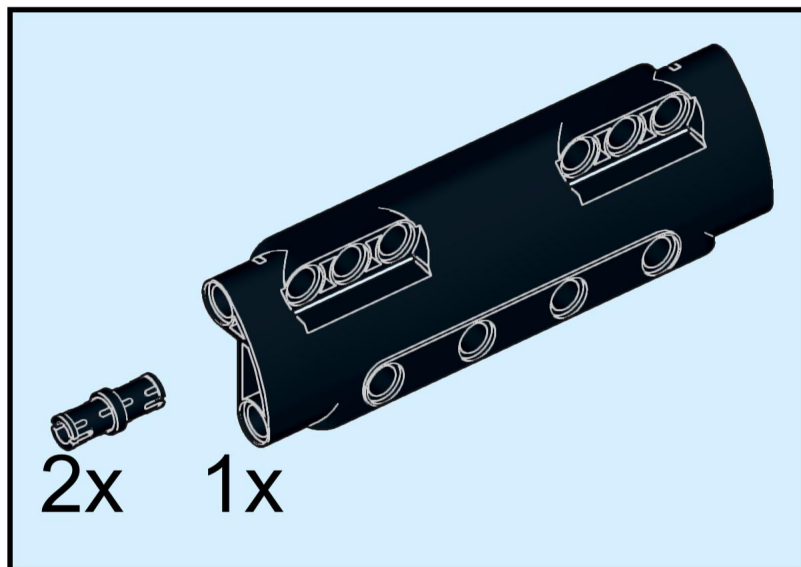
21



22



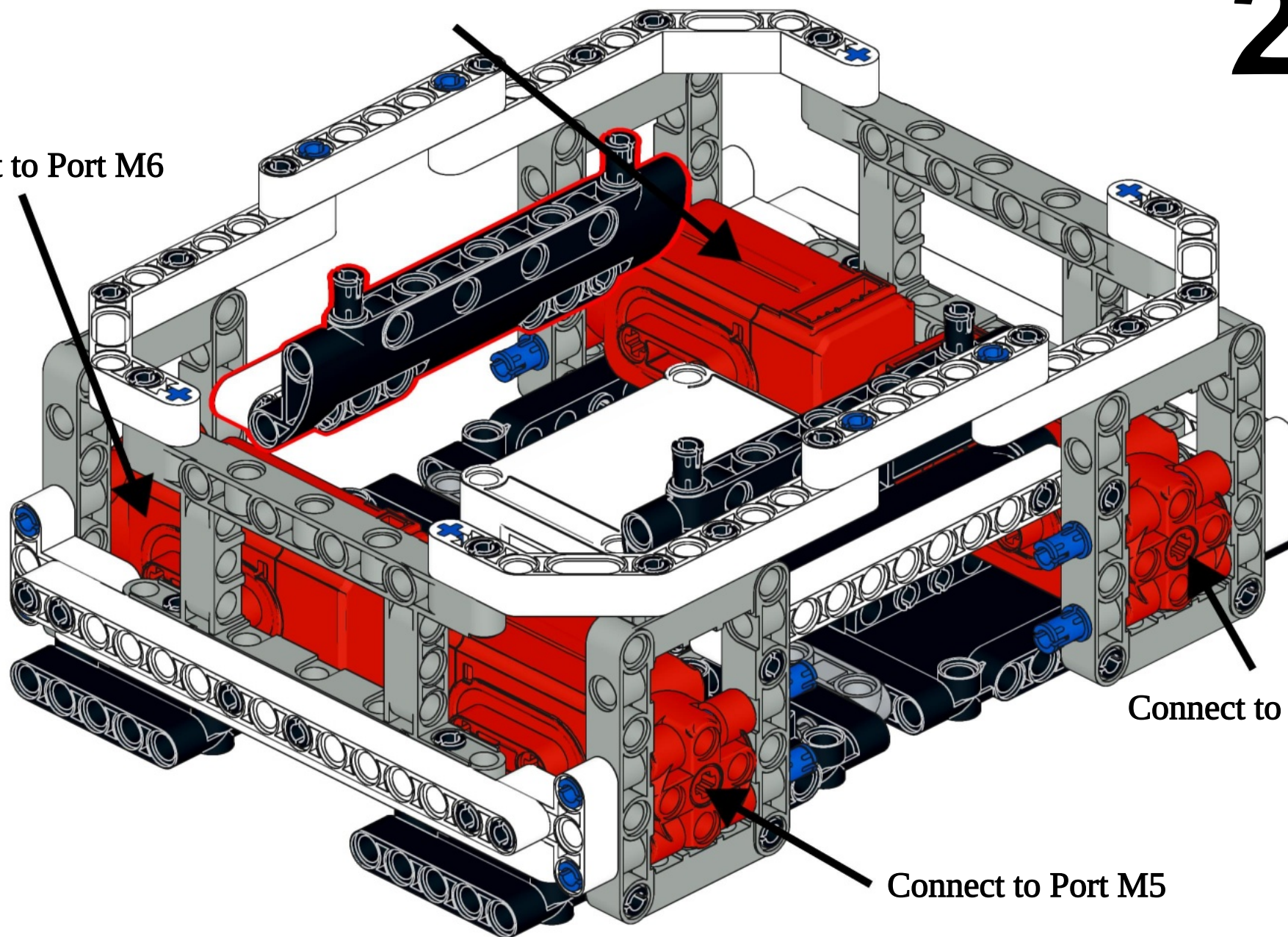




25

Connect to Port M4

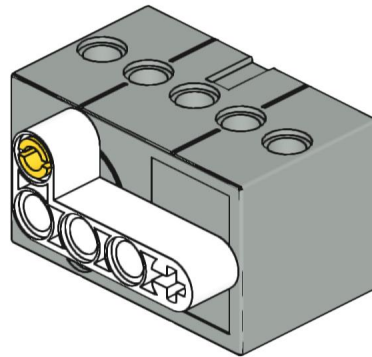
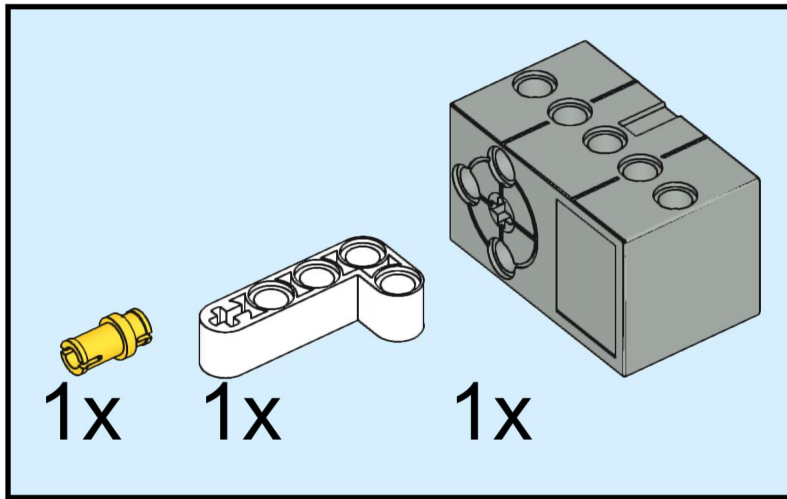
Connect to Port M6



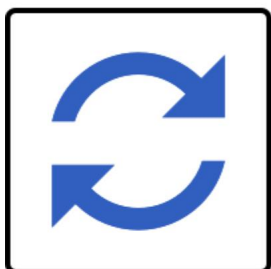
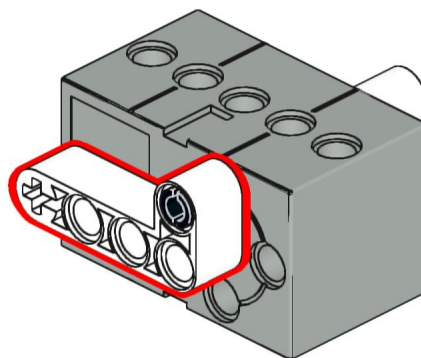
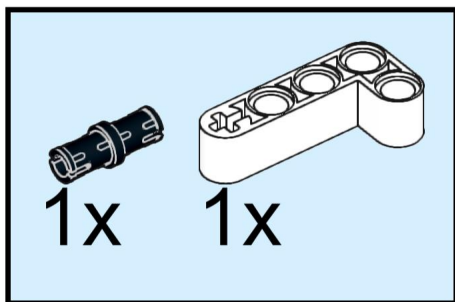
Connect to Port M3

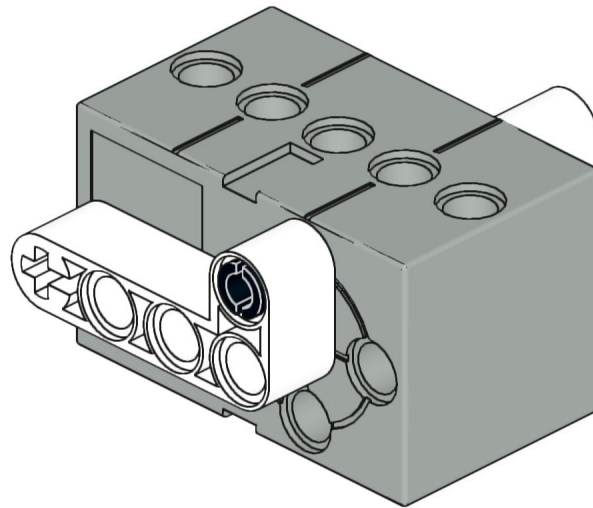
Connect to Port M5

26

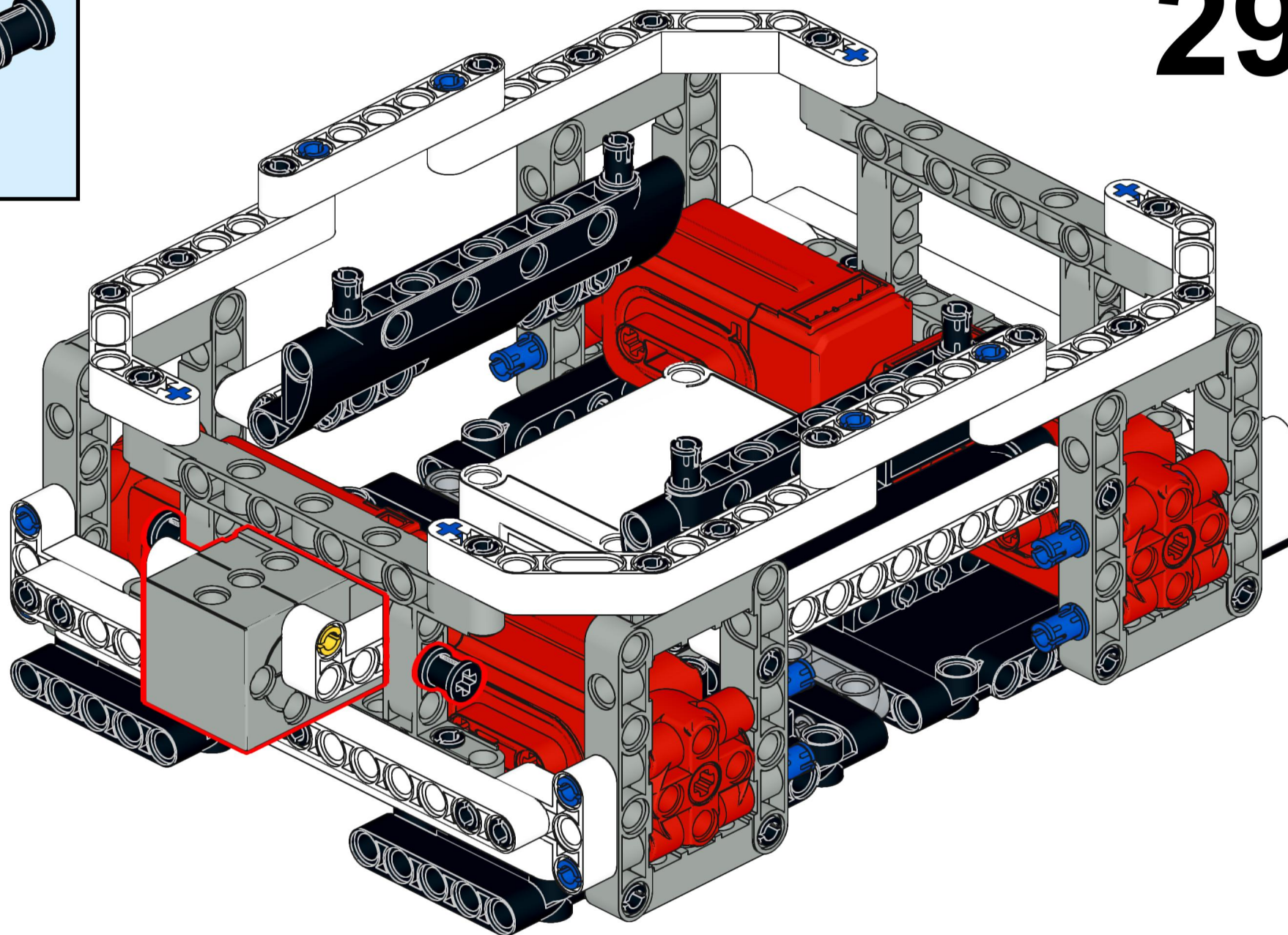
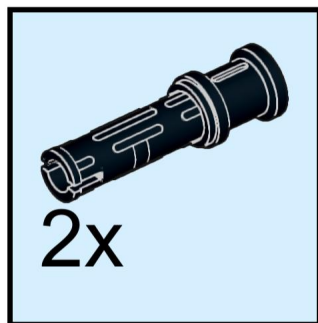


27

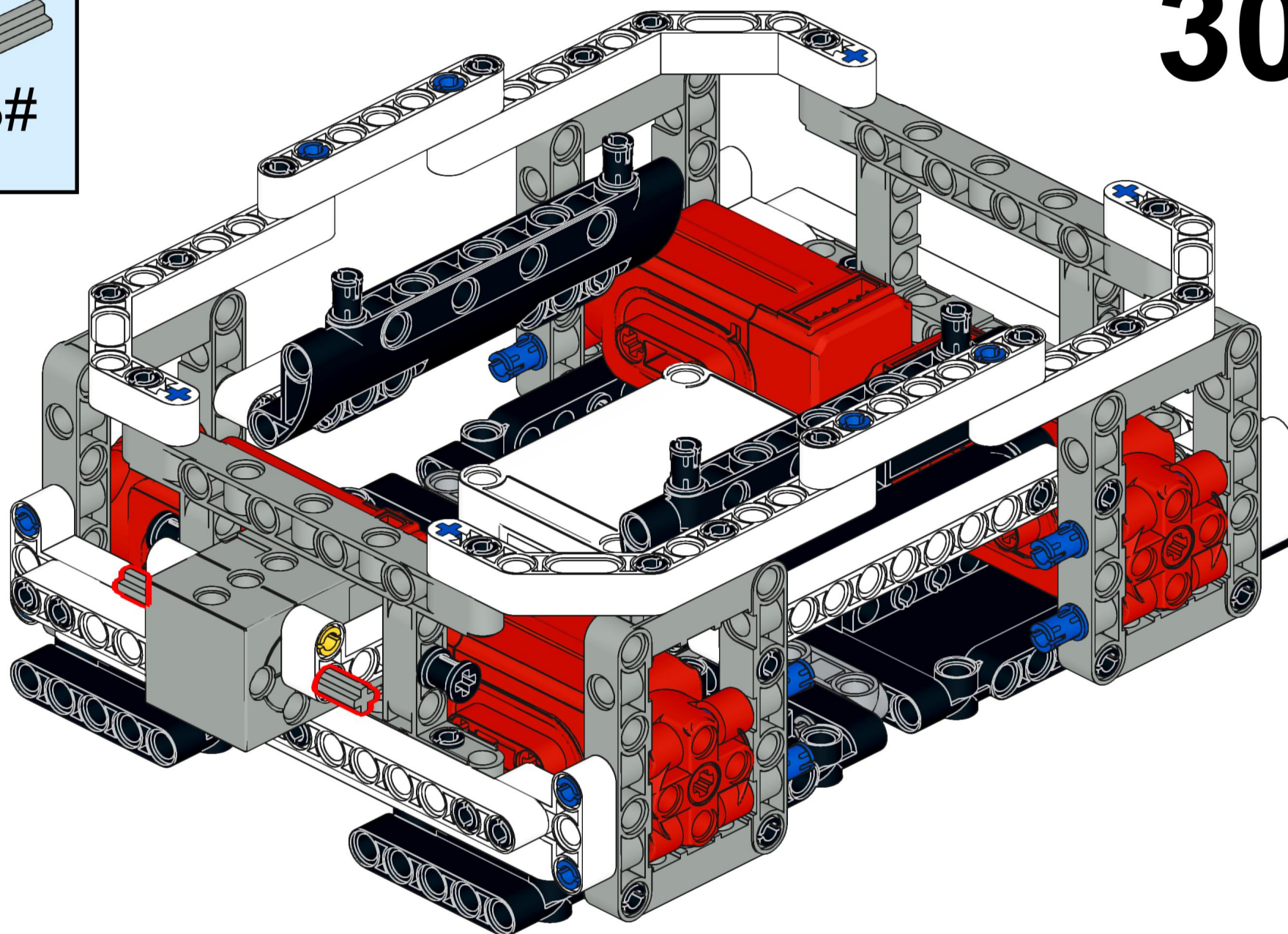
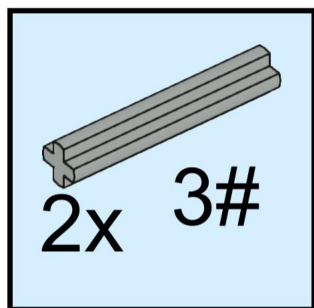




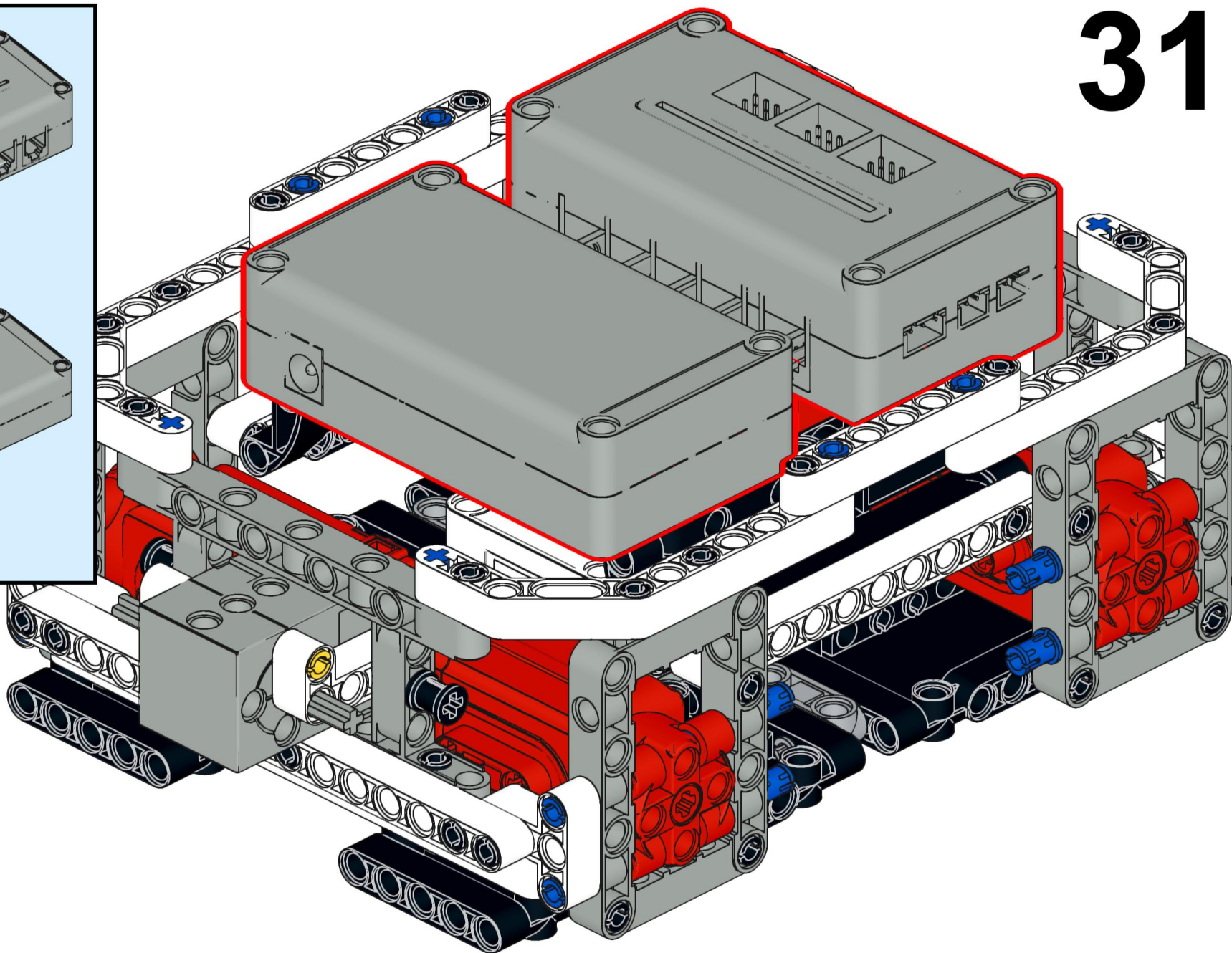
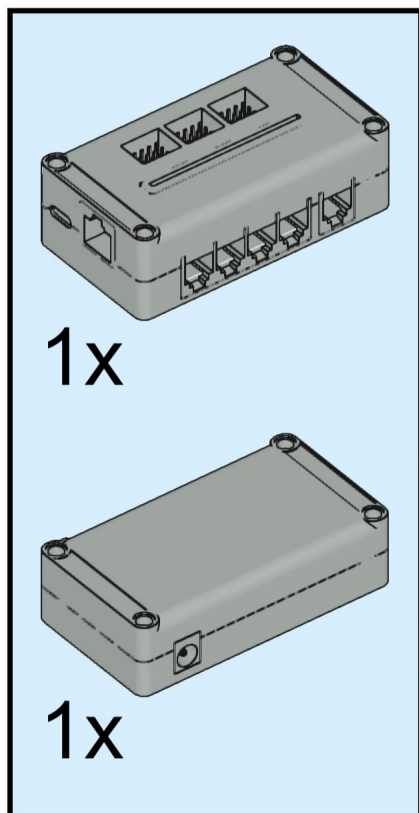
29



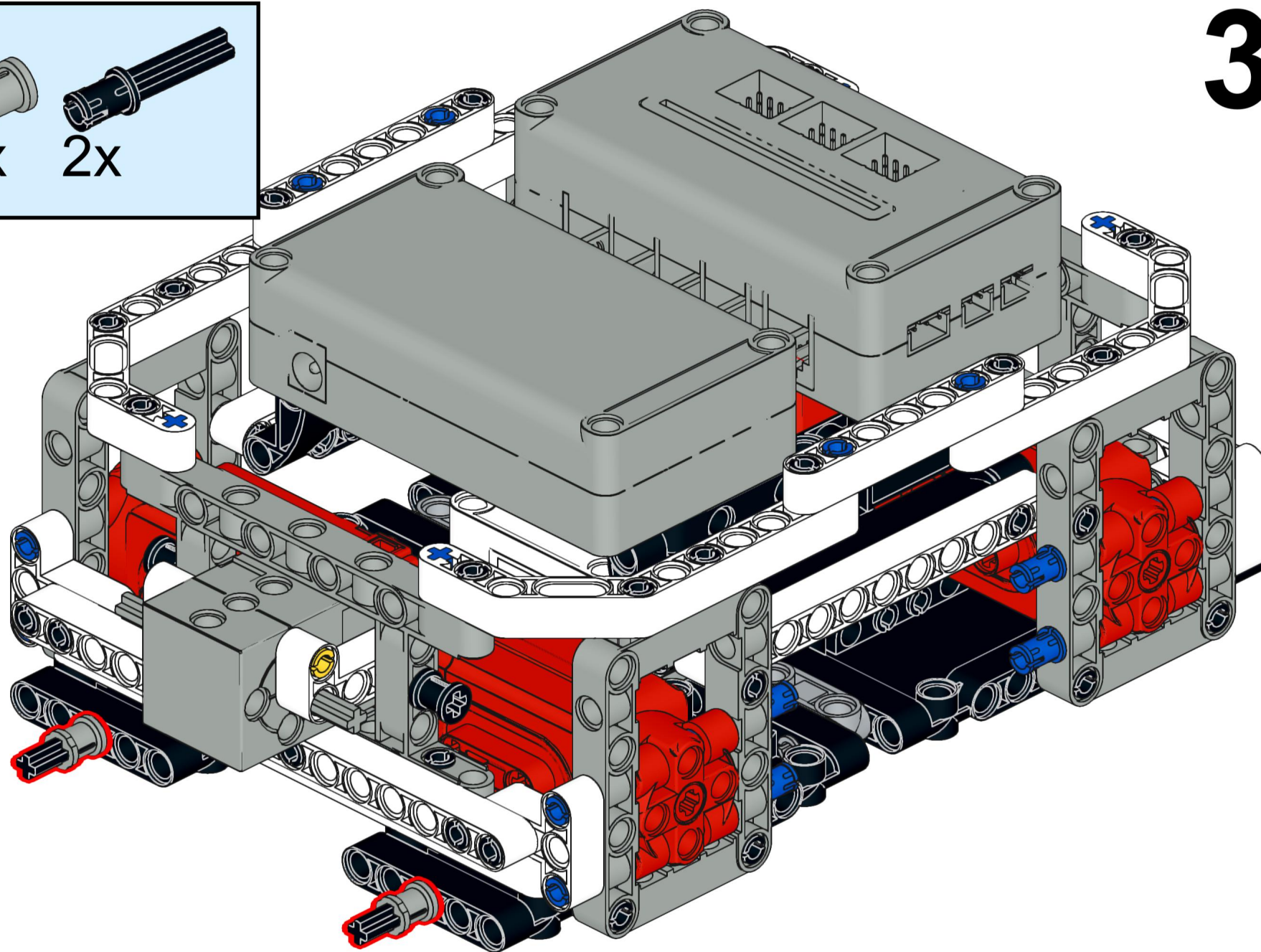
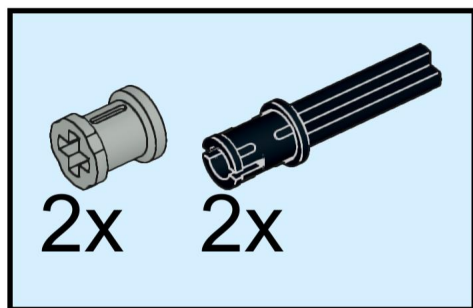
30



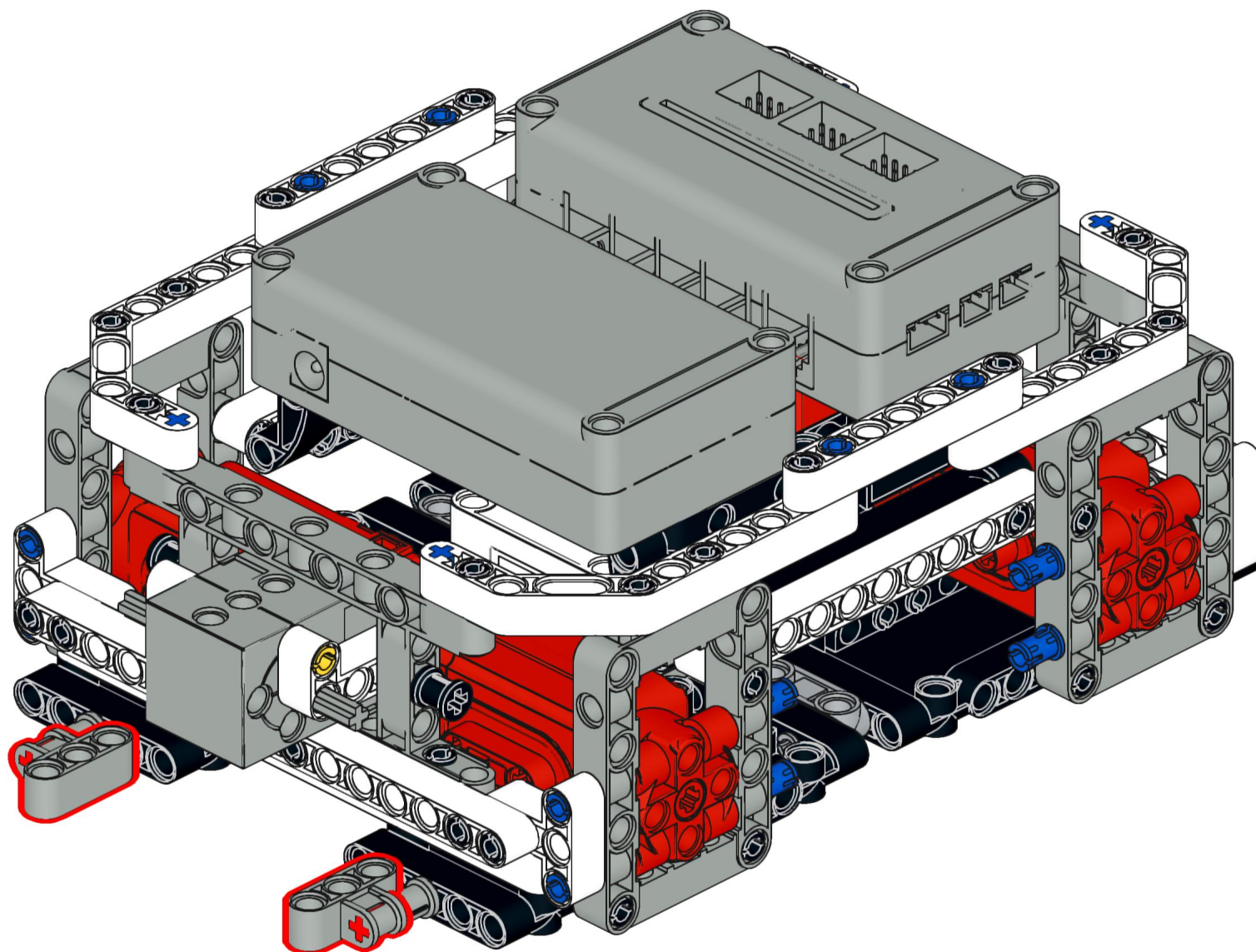
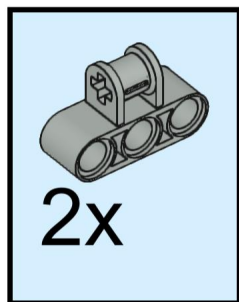
31



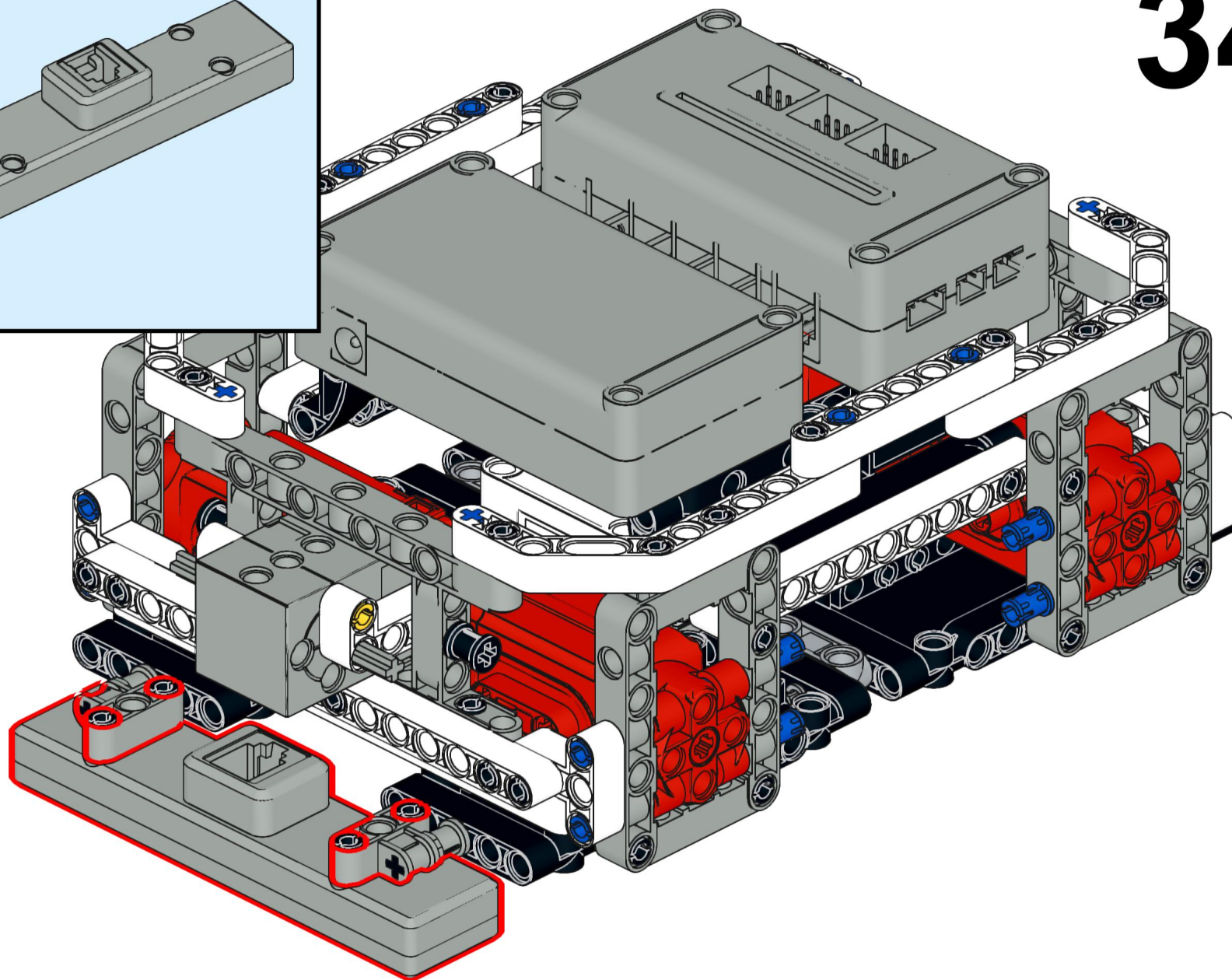
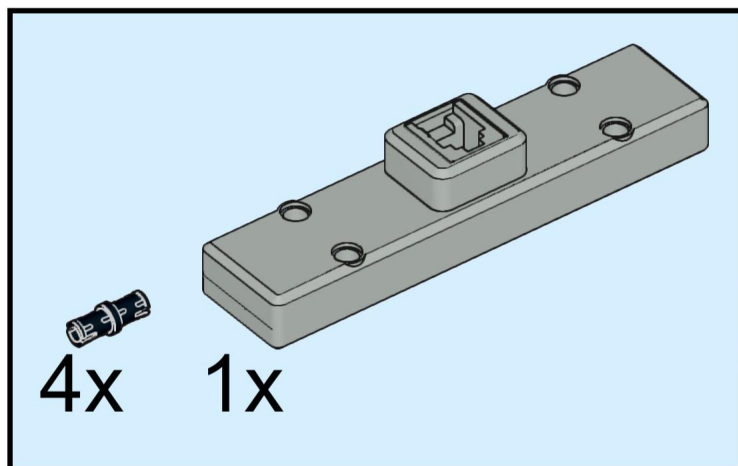
32

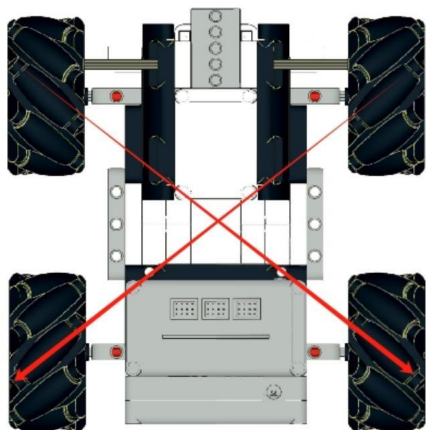
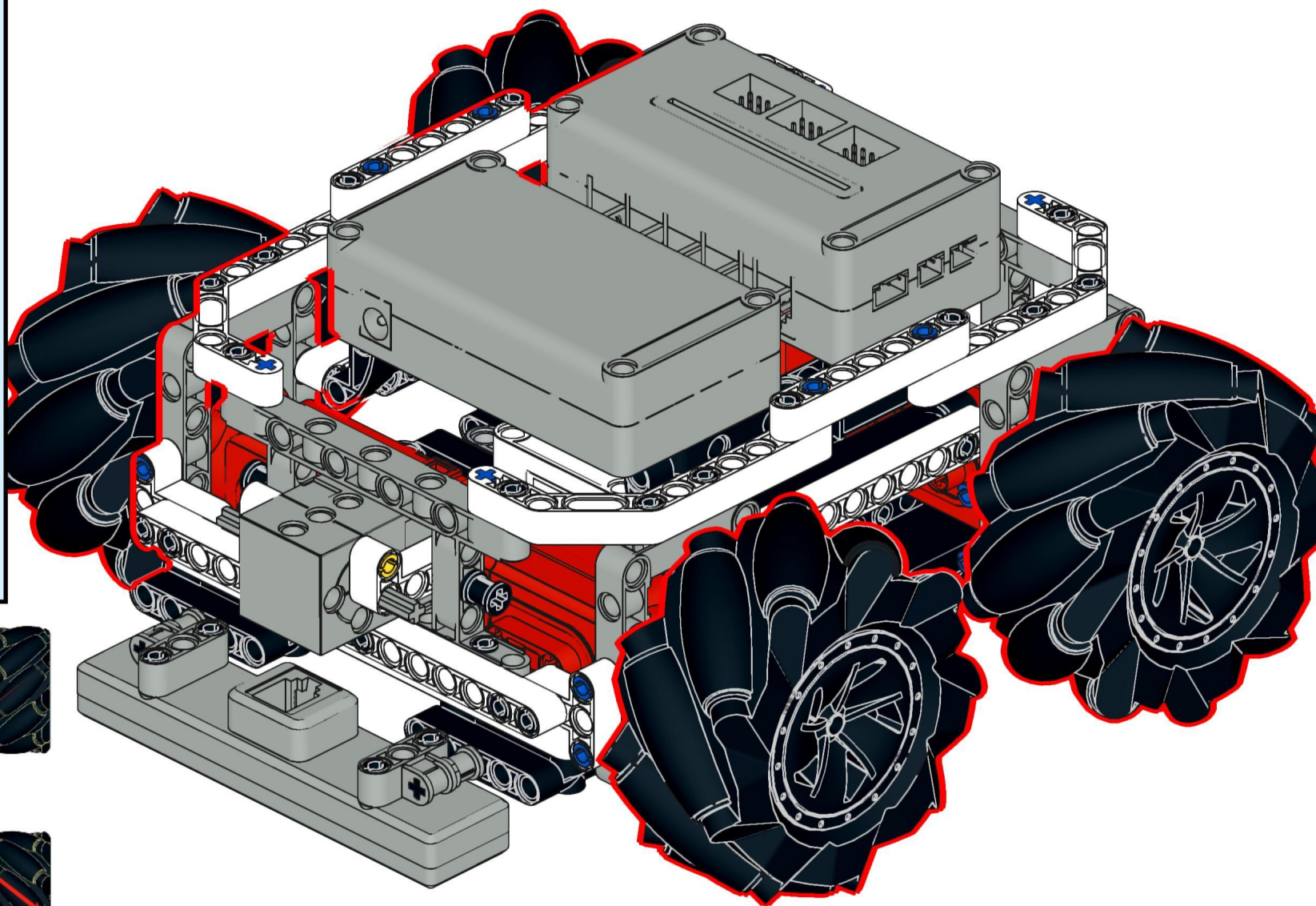
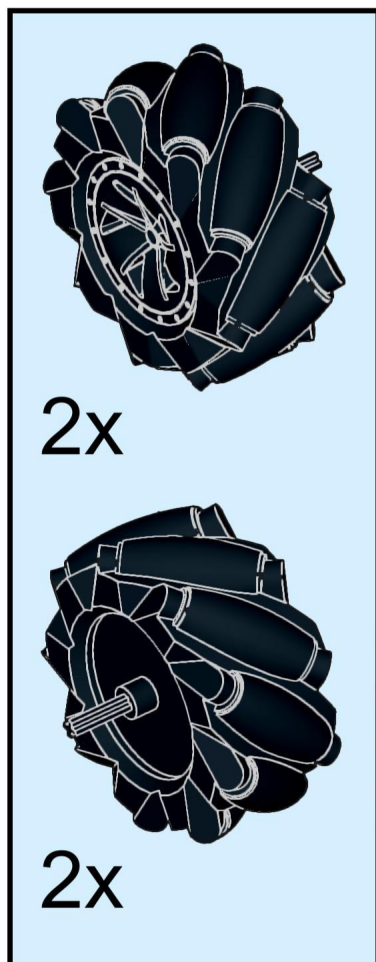


33



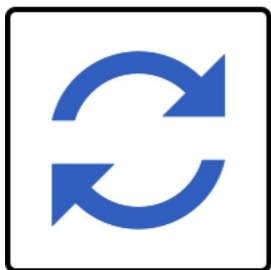
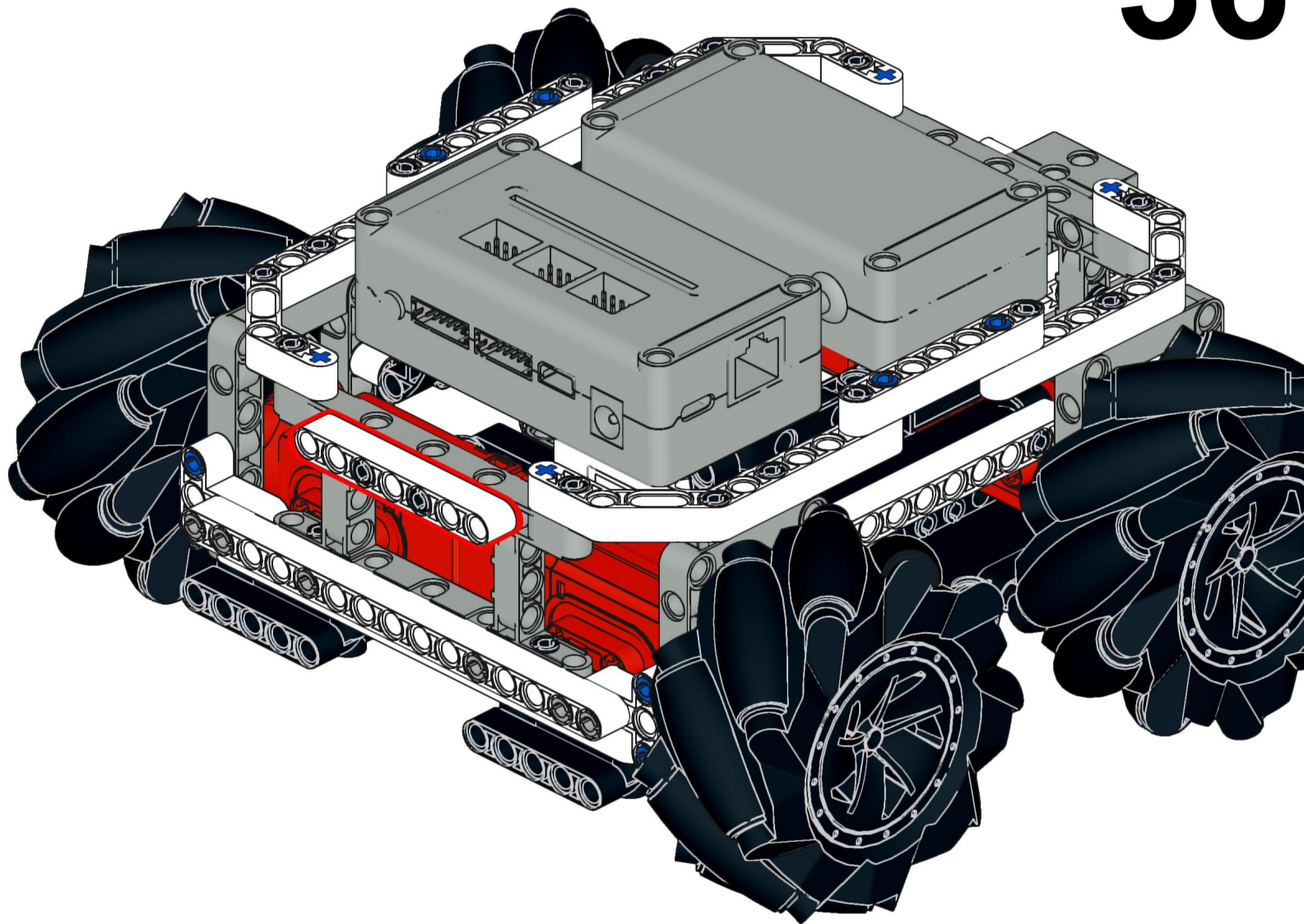
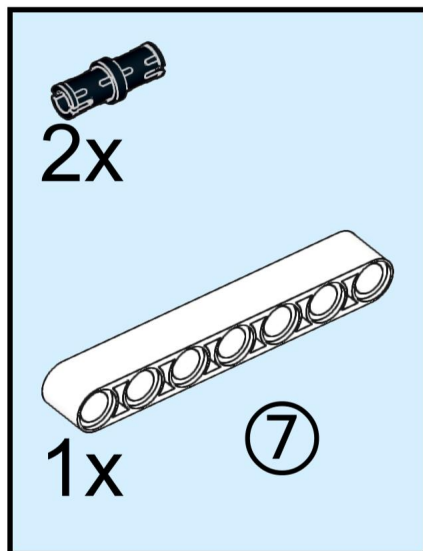
34

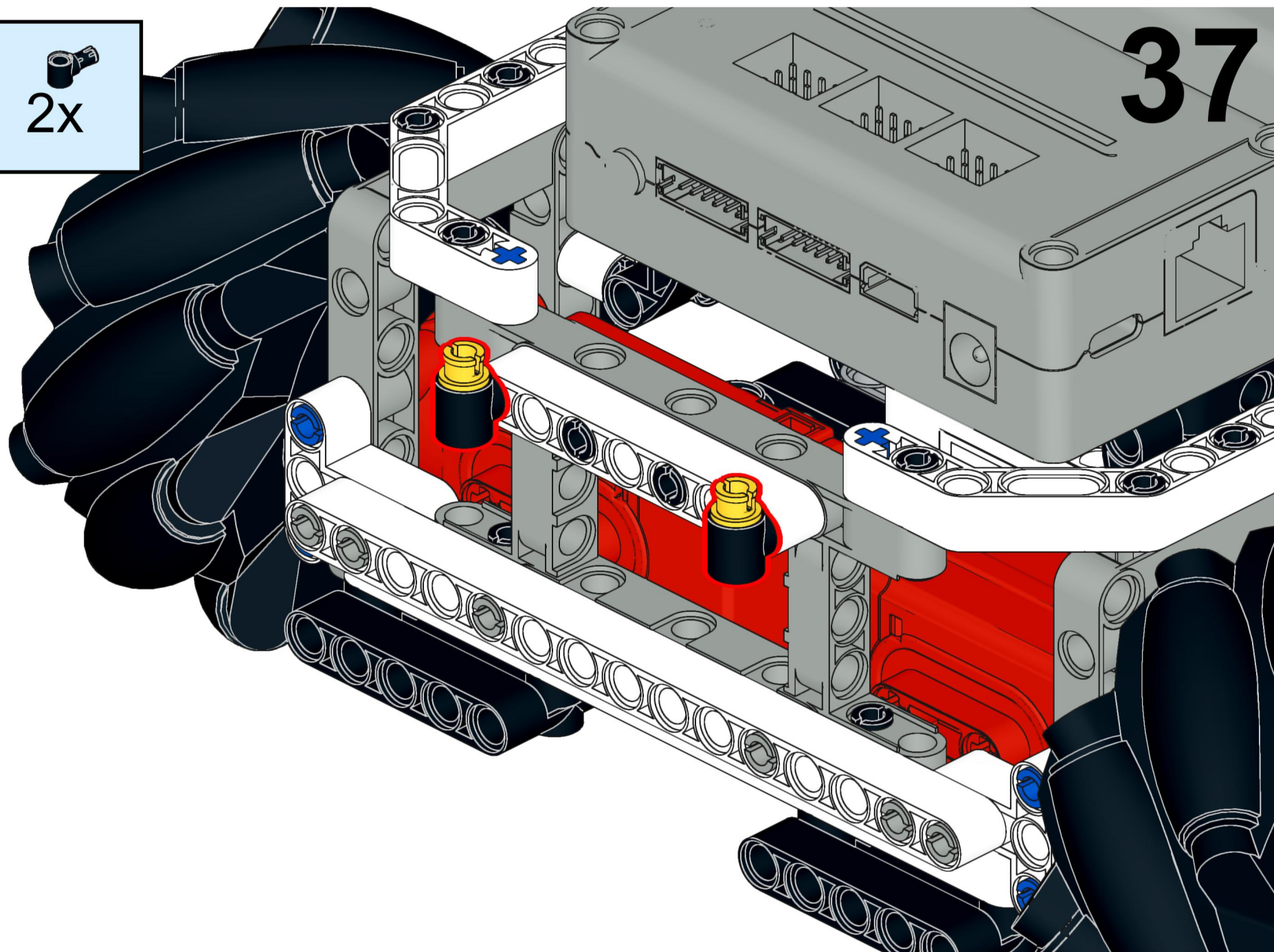


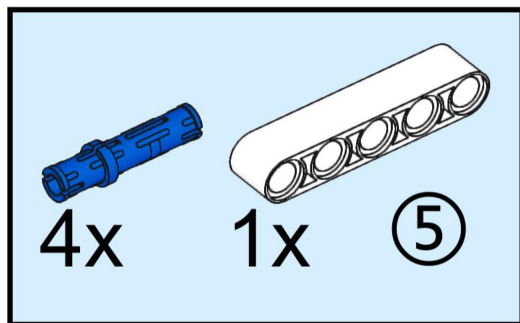


The Wheels are installed in an X shape.

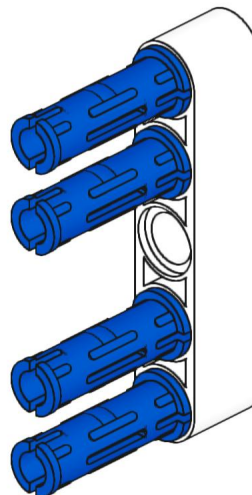
36

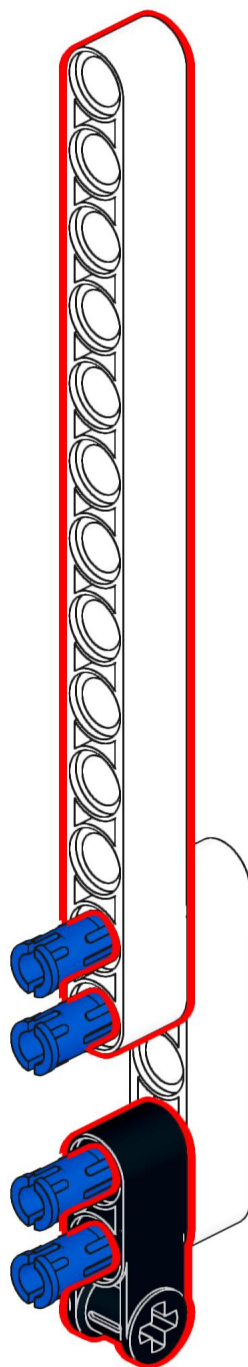
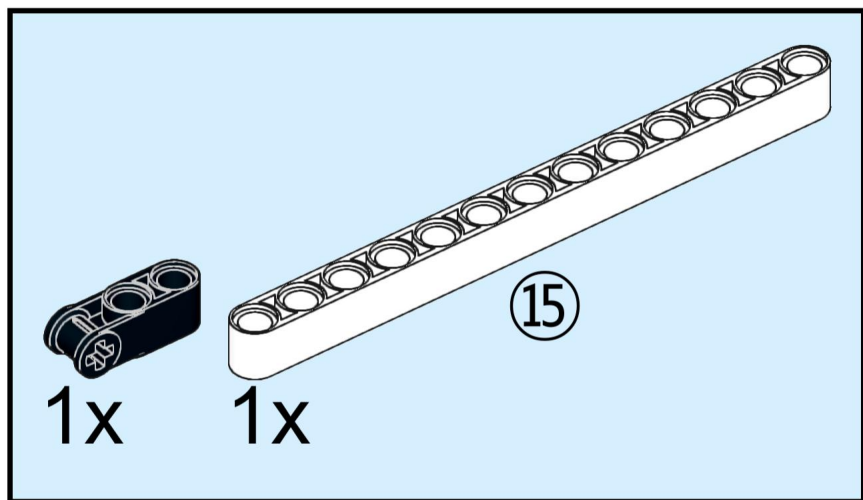




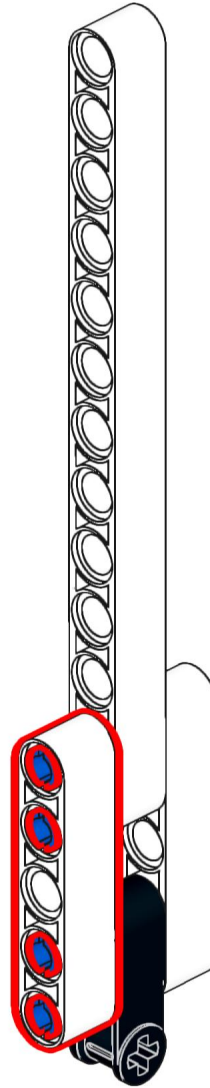
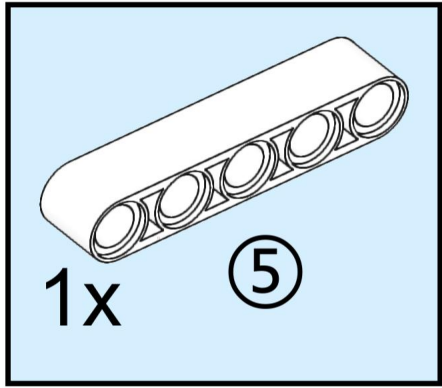


38

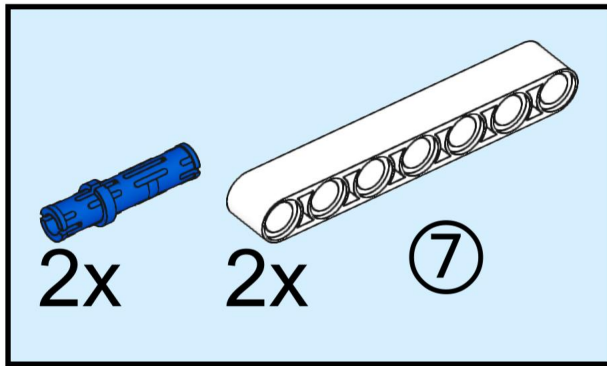




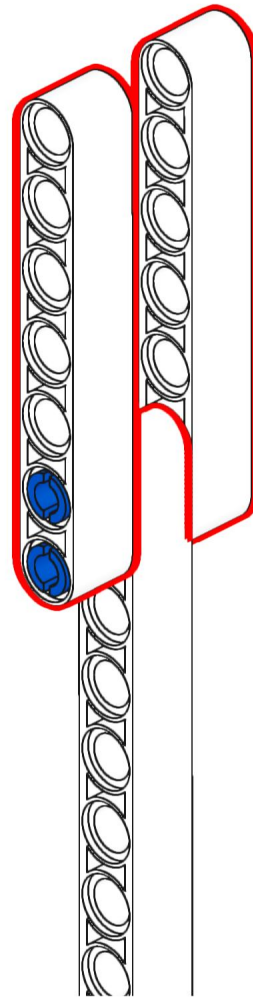
39

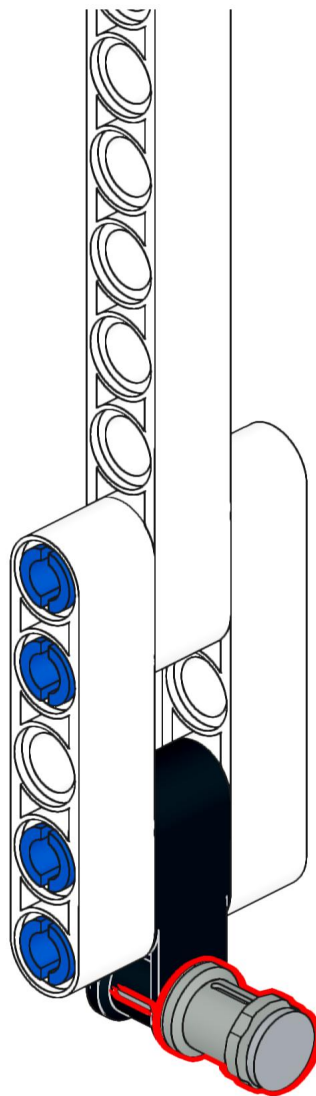
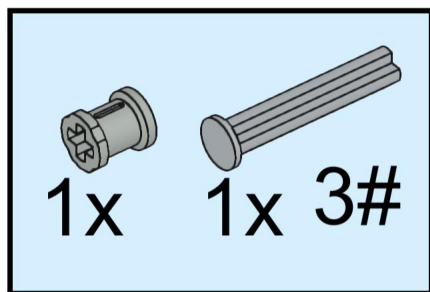


40

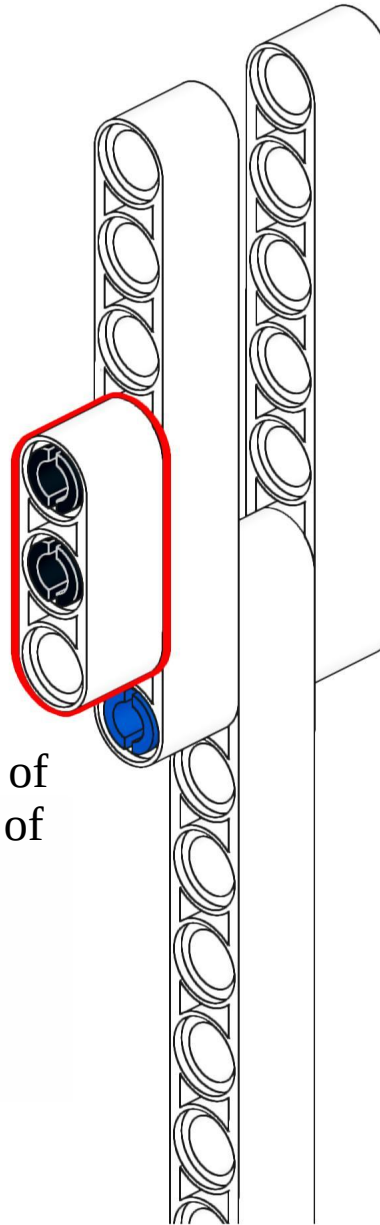
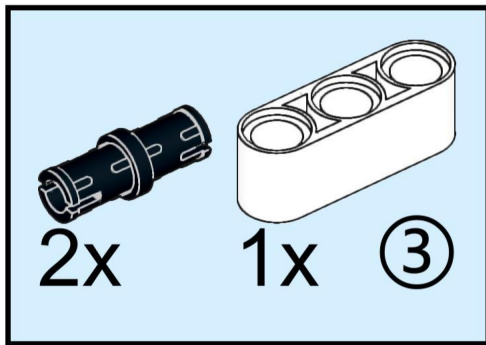


41

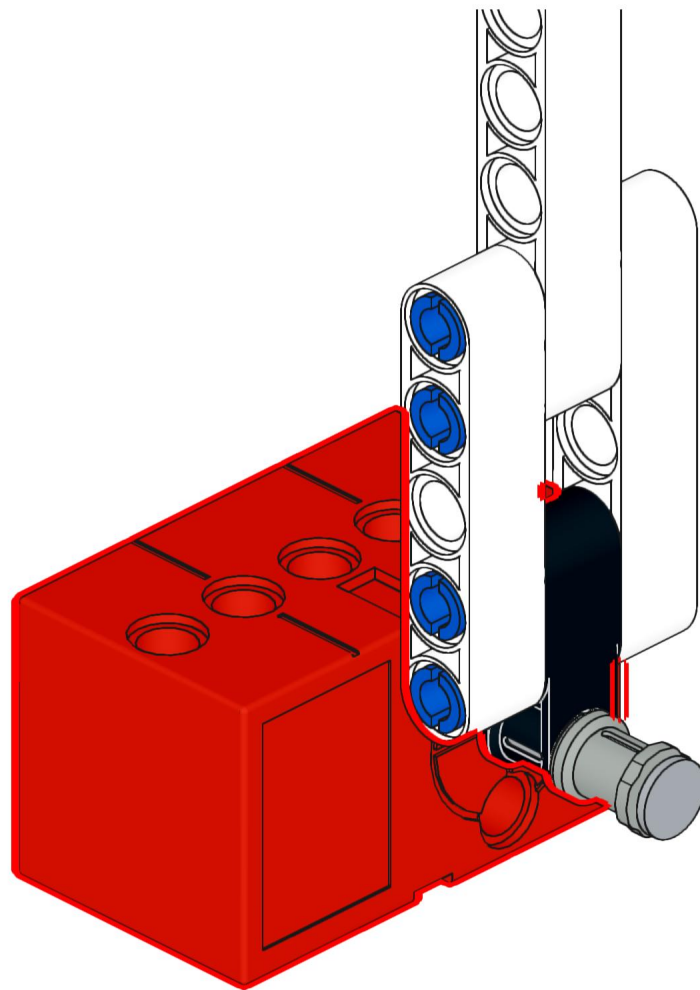
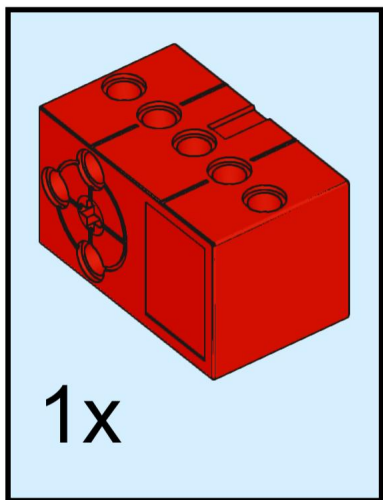




42

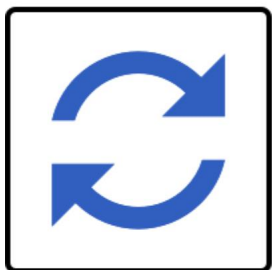
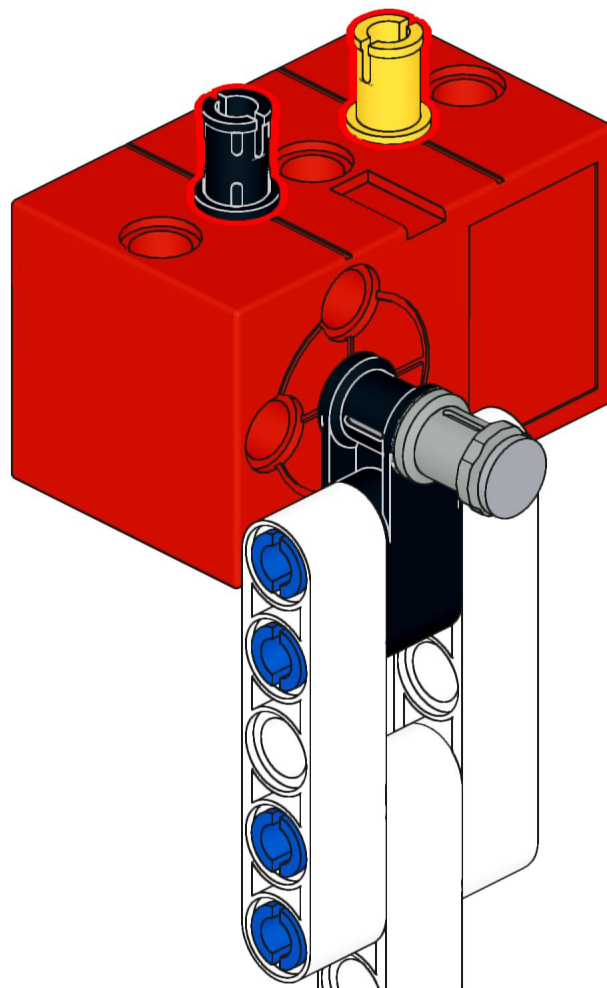
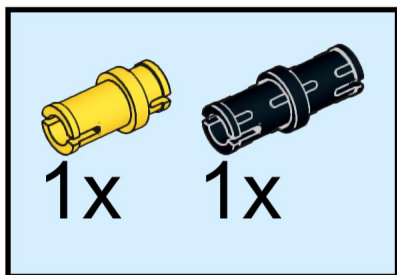


This three-hole beam is installed on one side of the "pest" model, depending on the location of the "pest" model in the mission.

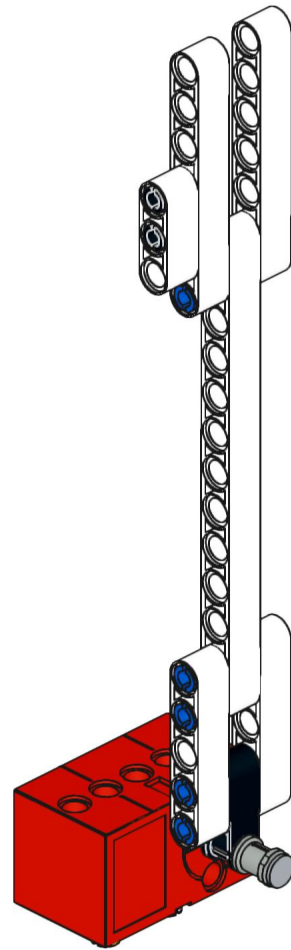


44

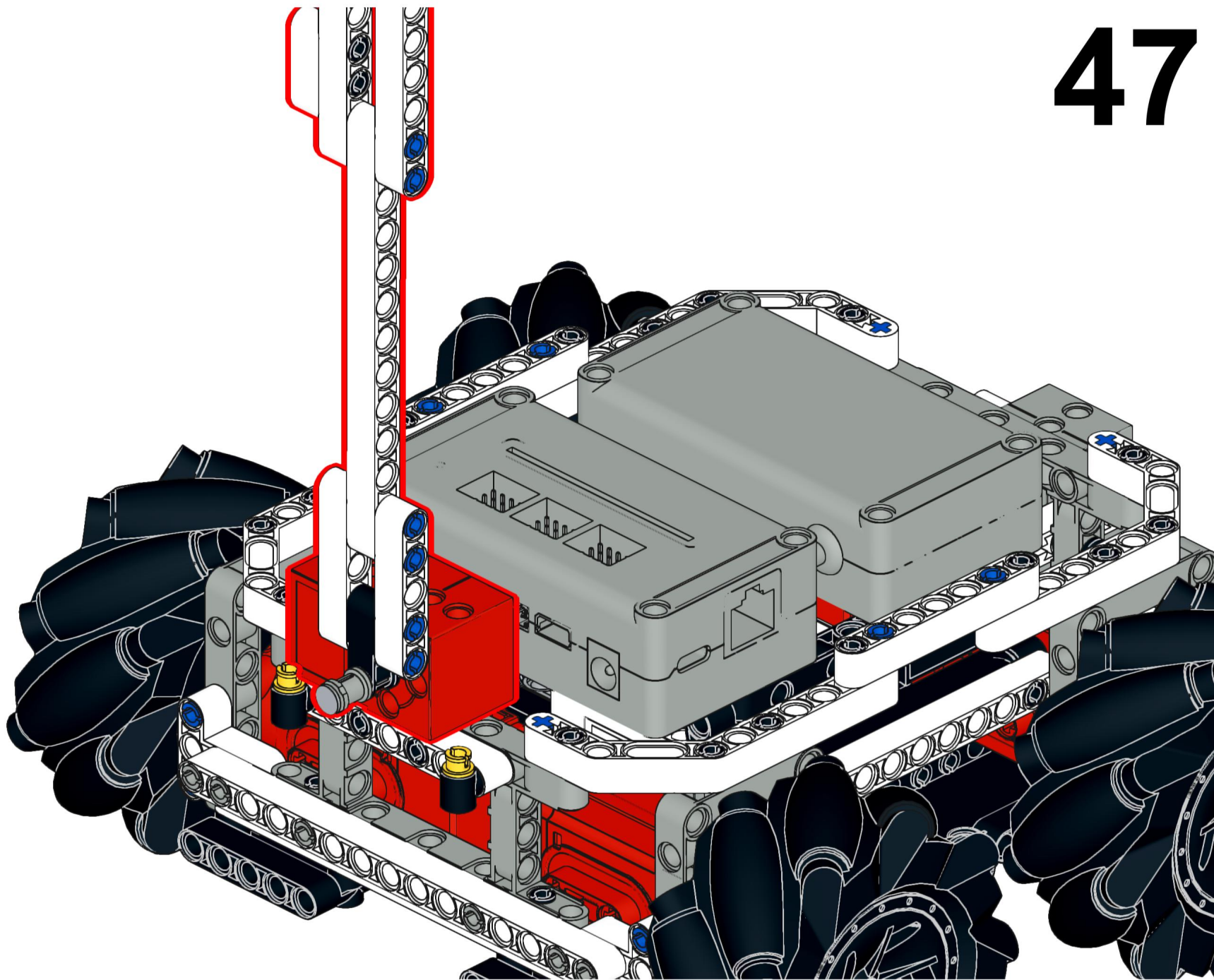
45



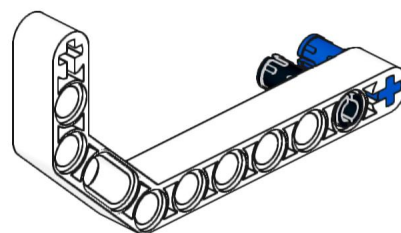
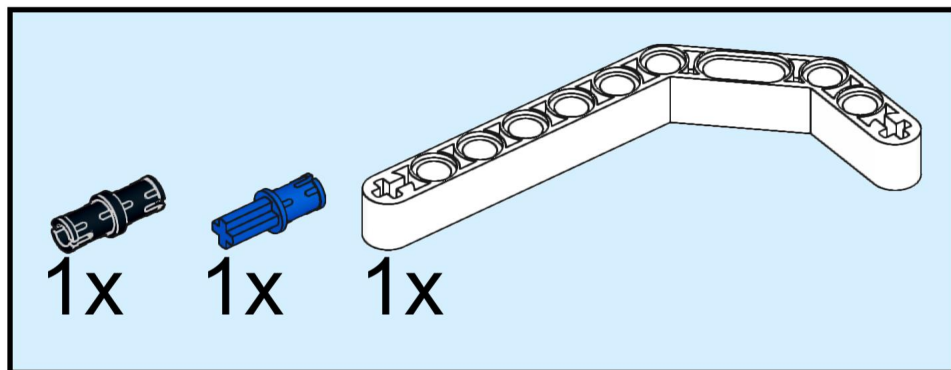
46

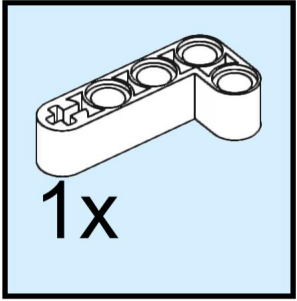


47

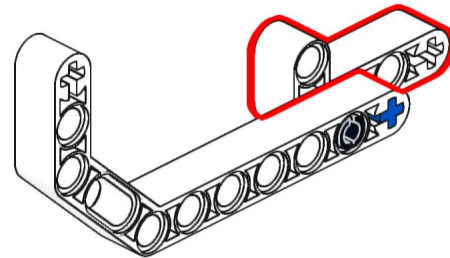


48

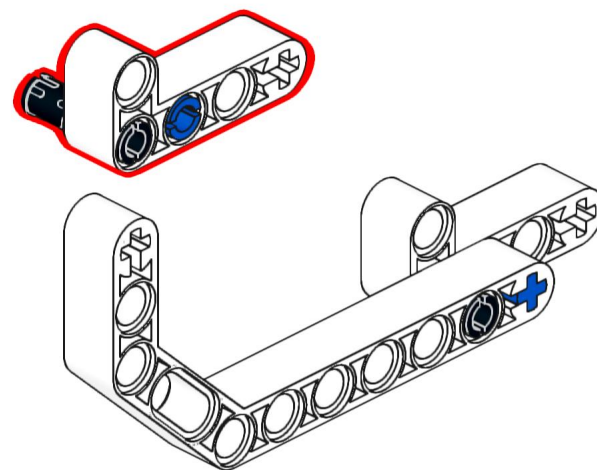
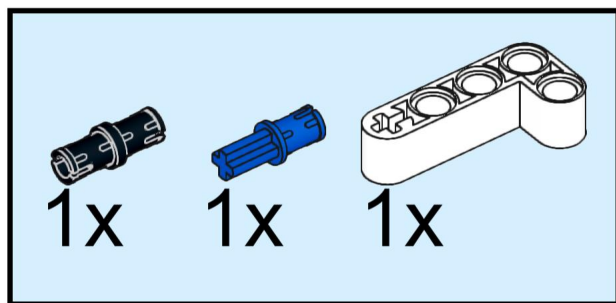




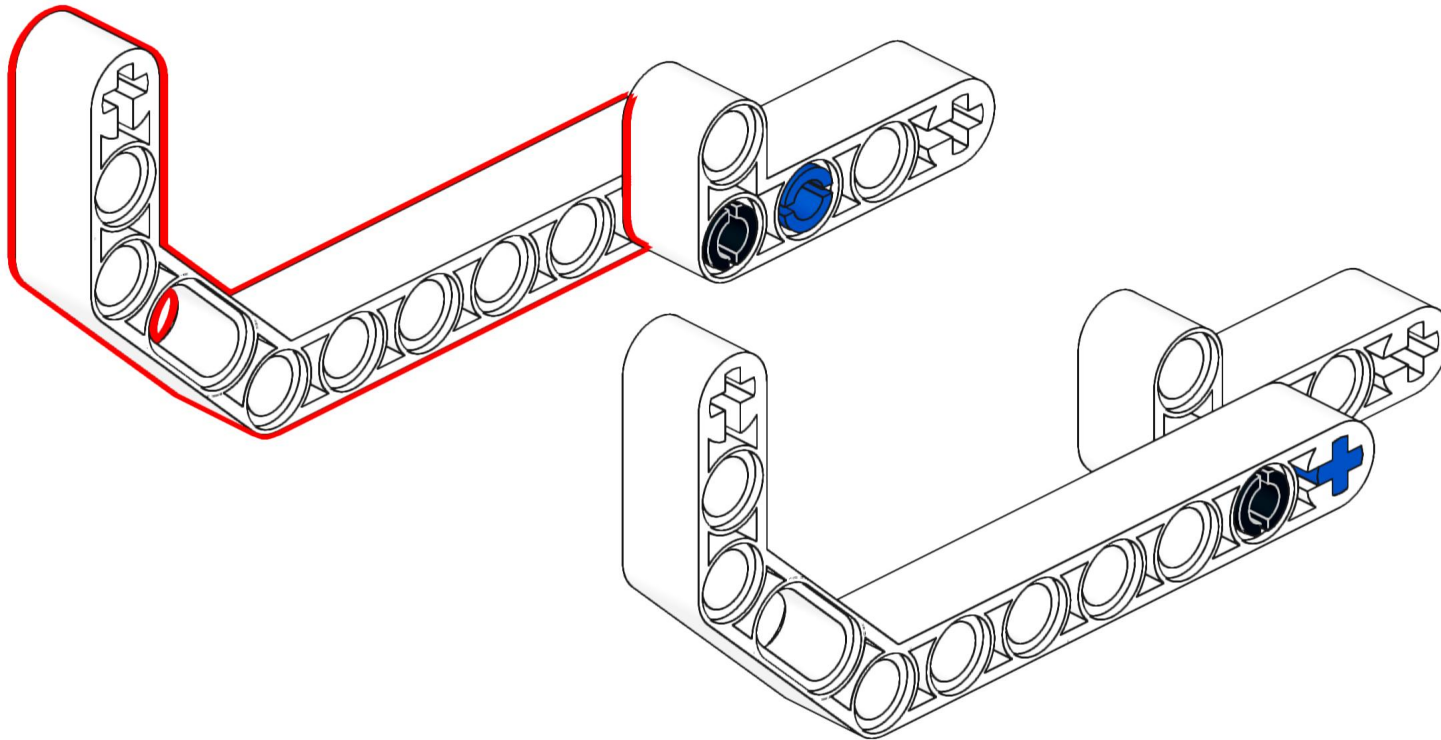
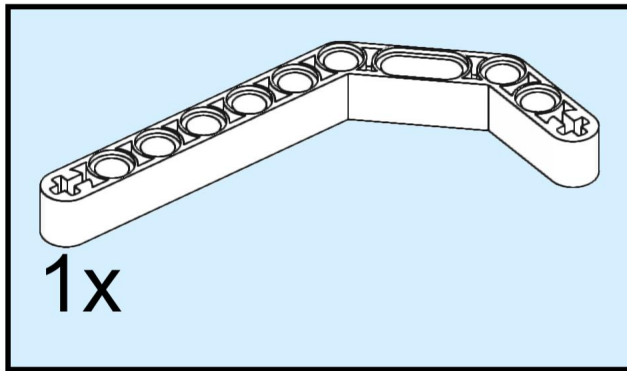
49

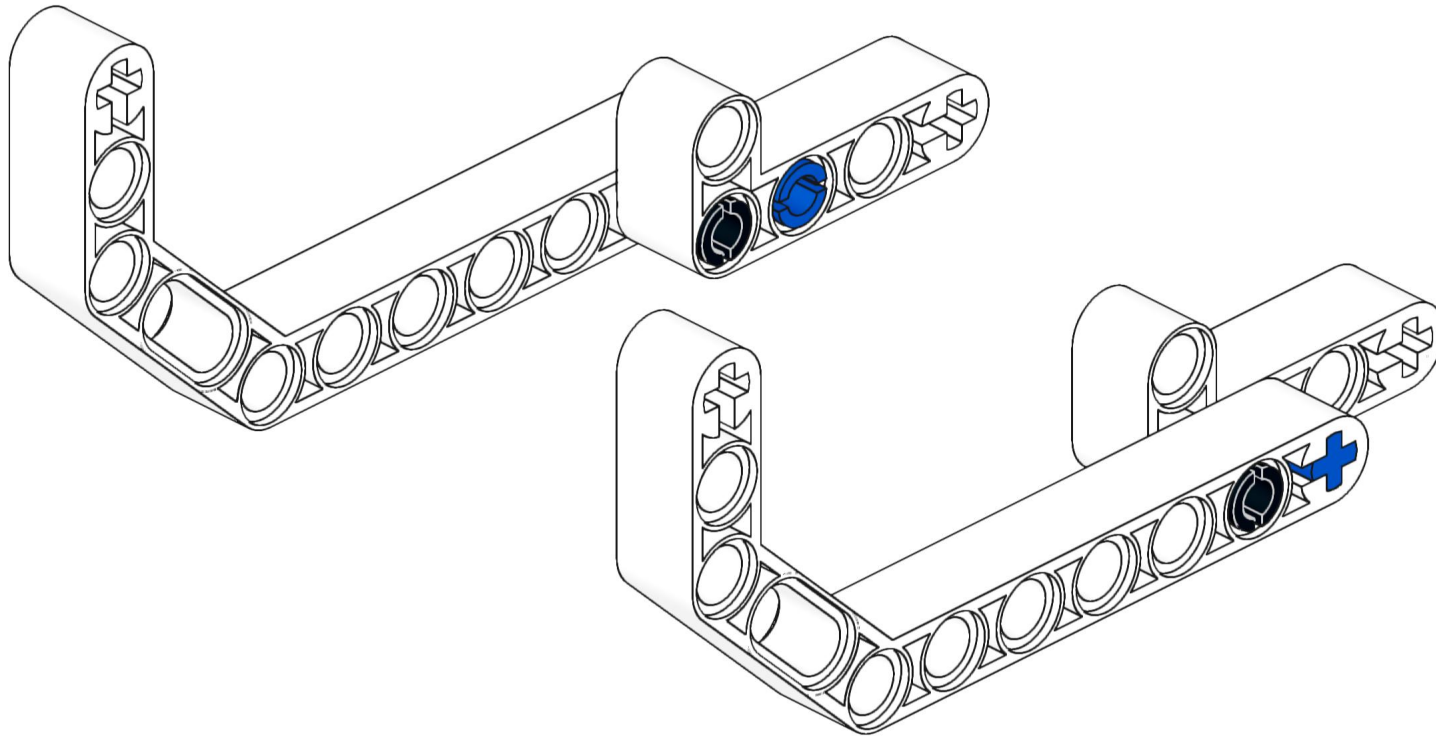


50

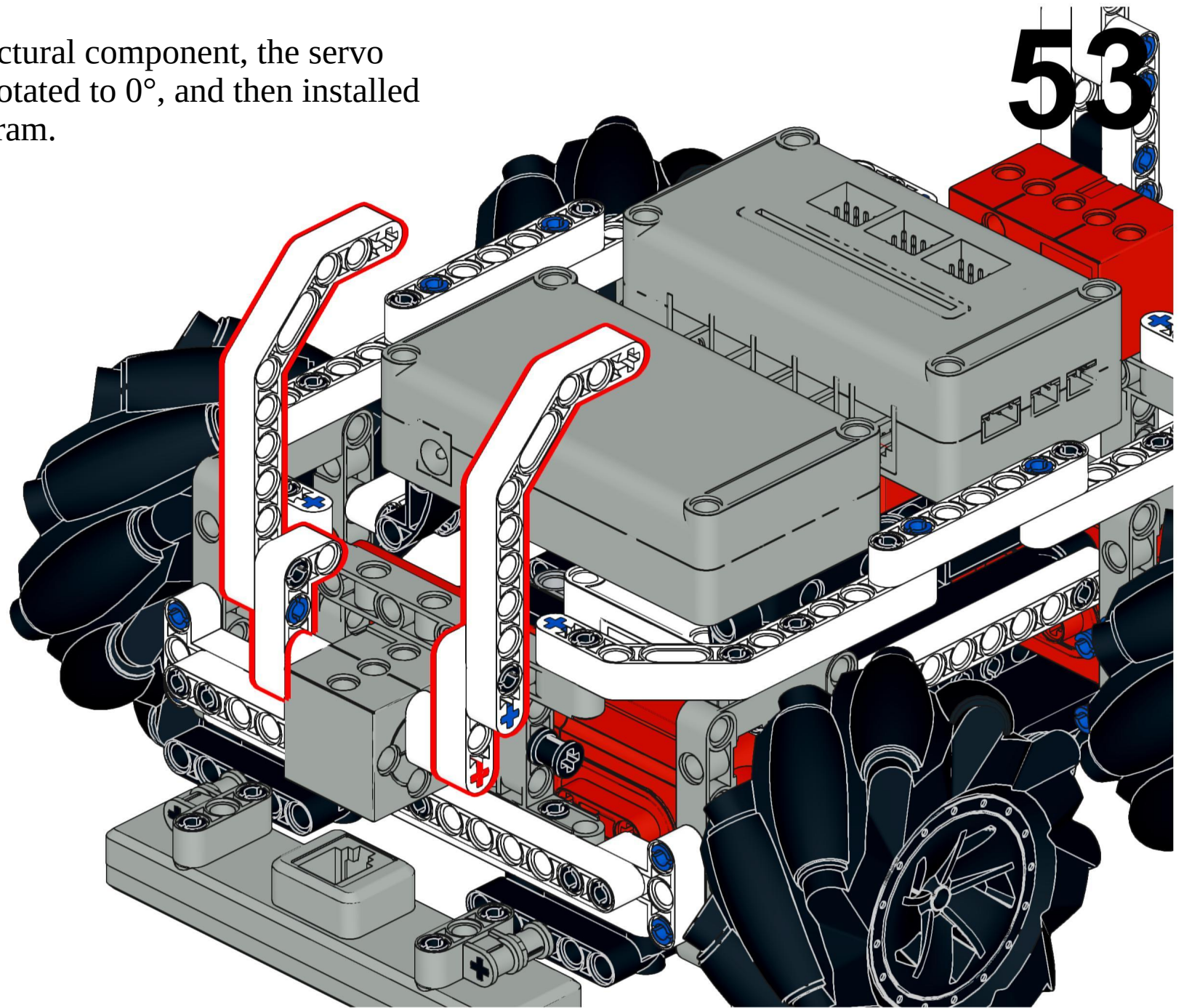


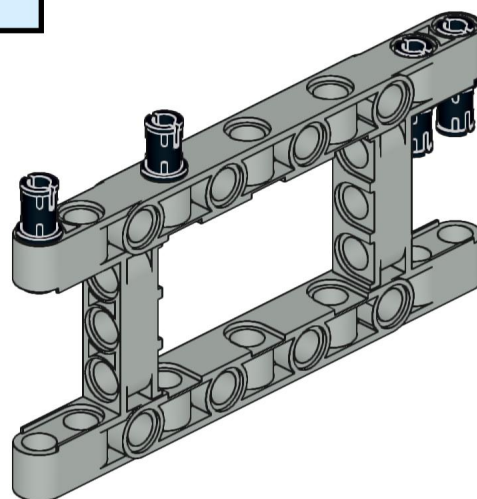
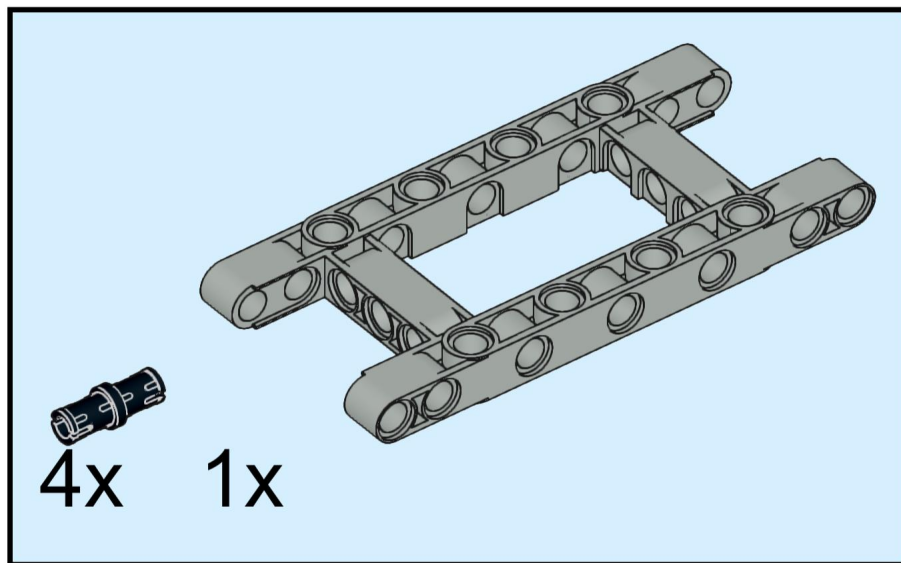
51

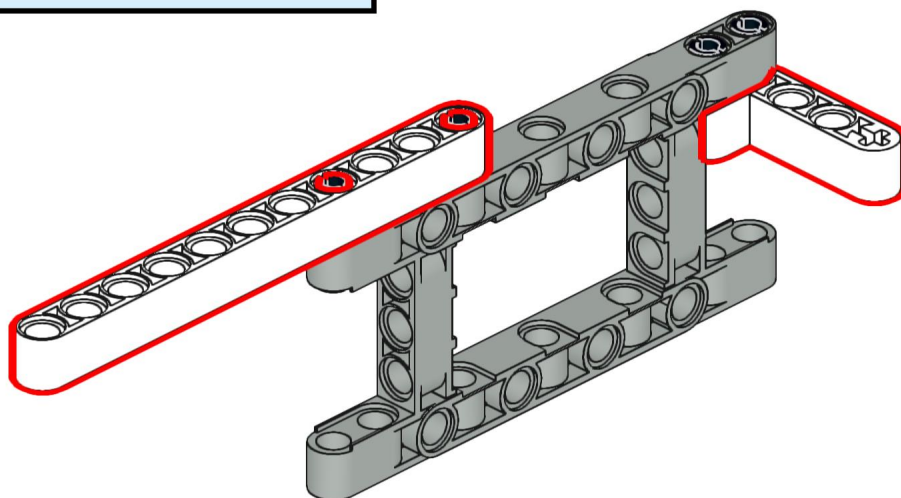
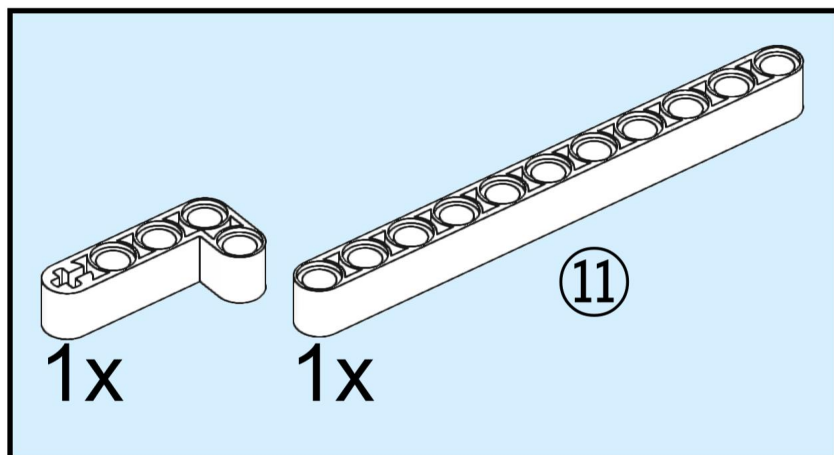


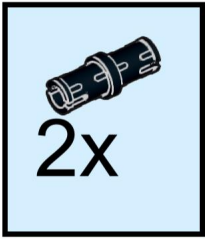


When using this structural component, the servo motor must first be rotated to 0°, and then installed as shown in the diagram.

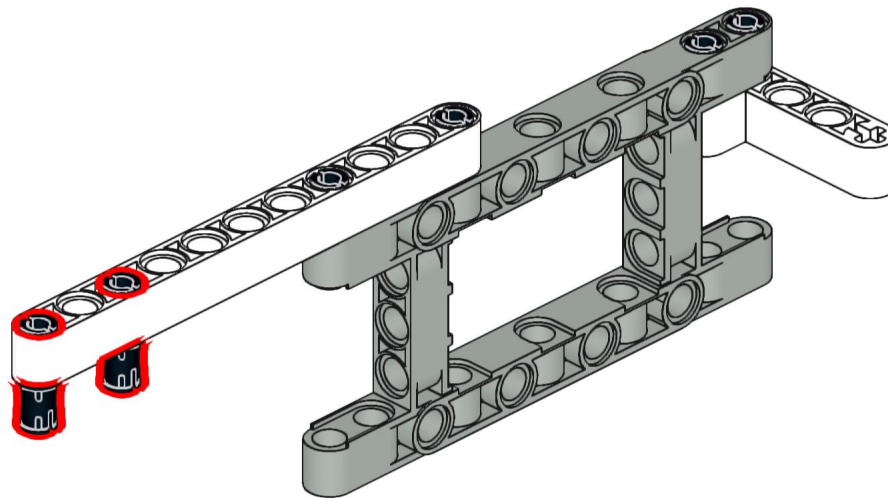




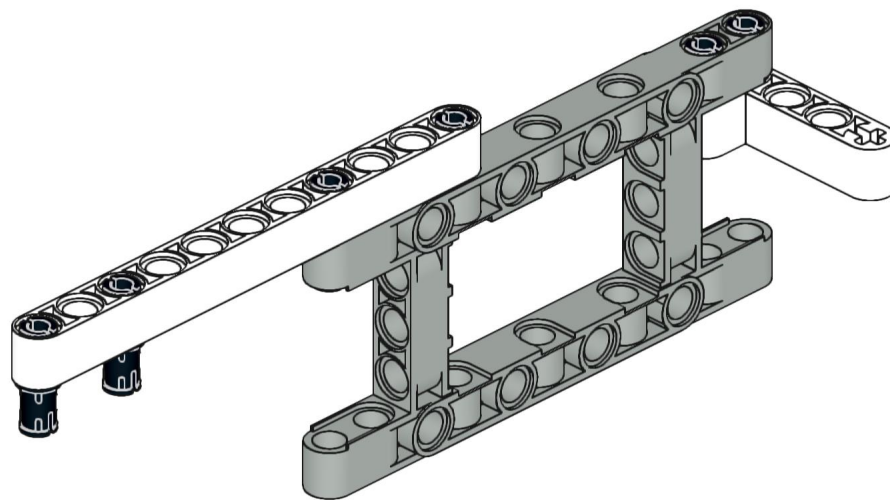




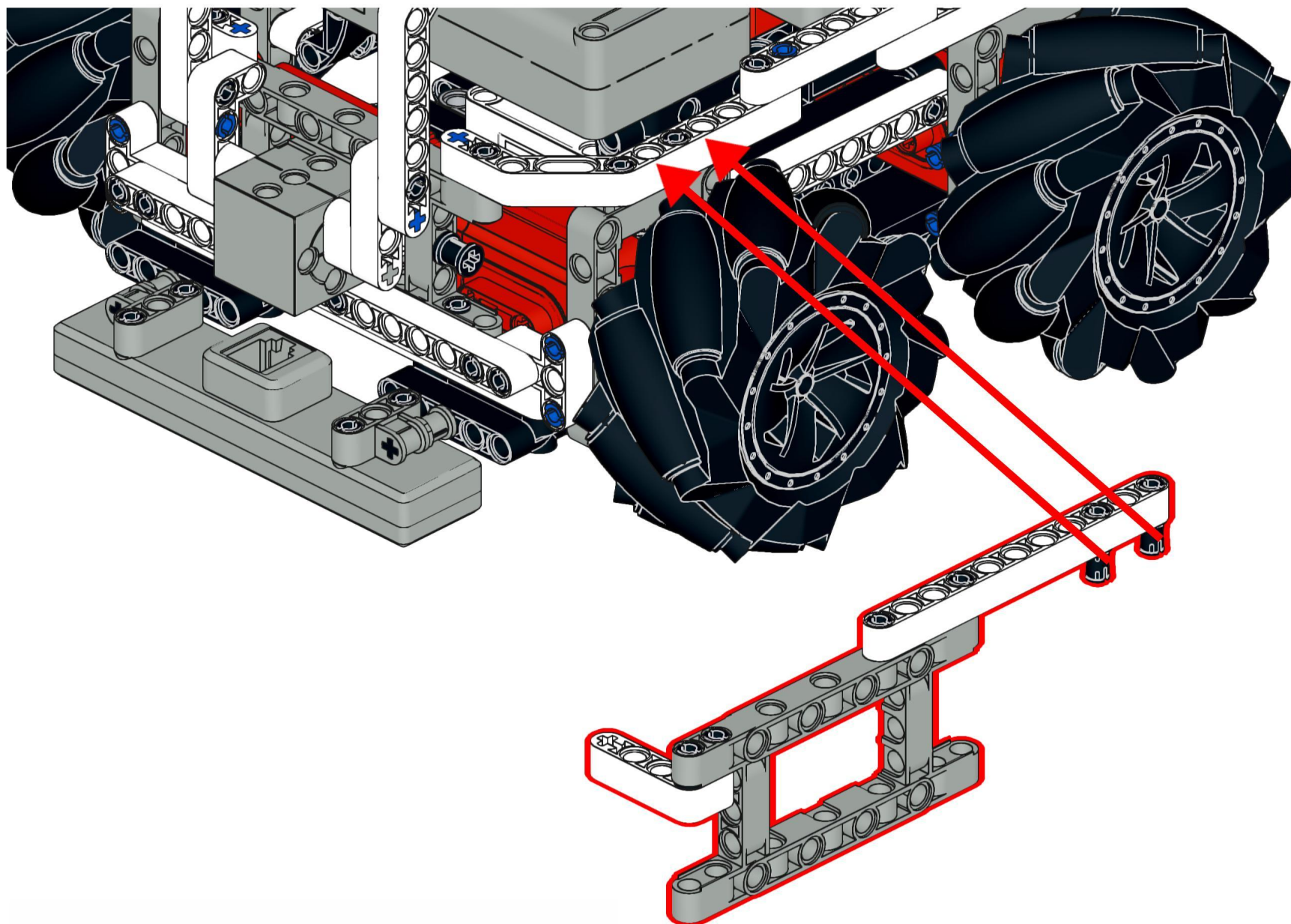
56



57

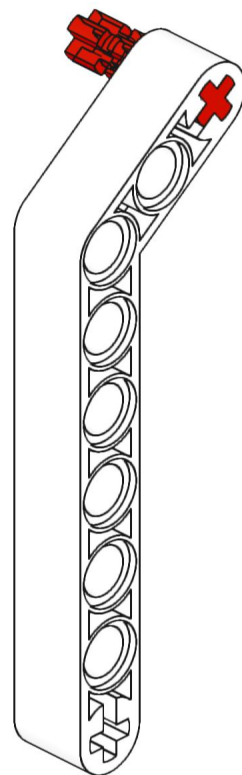
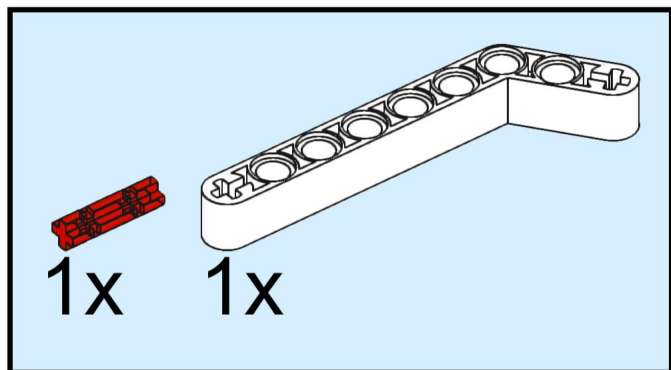


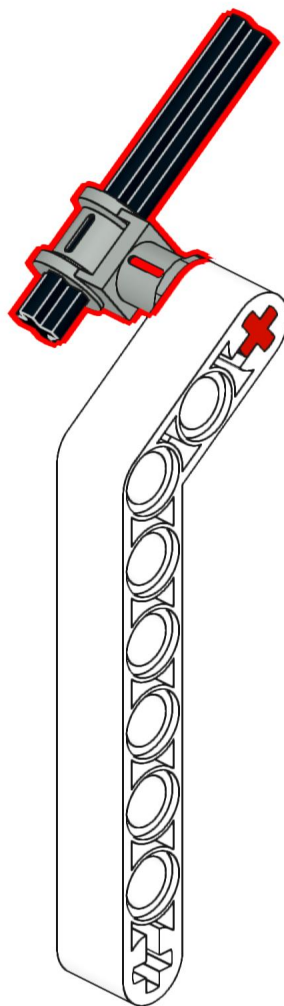
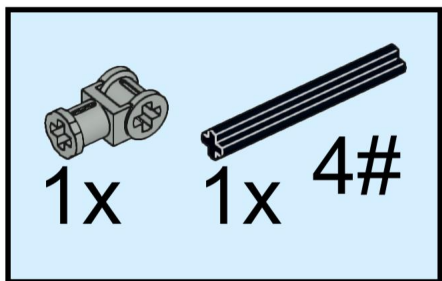
58



The task of using this structural component is to install it into the two holes shown in the diagram above.

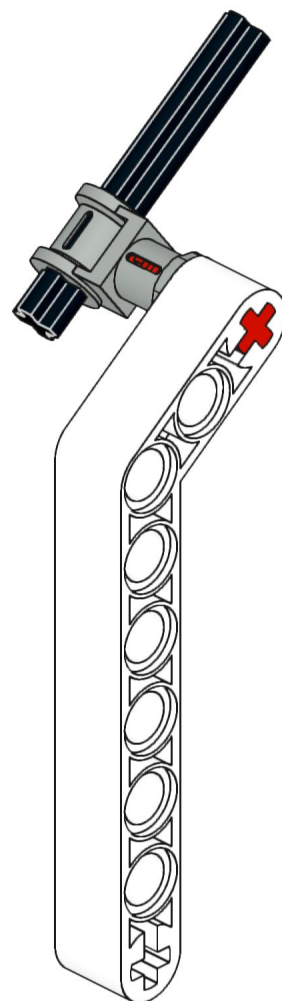
59

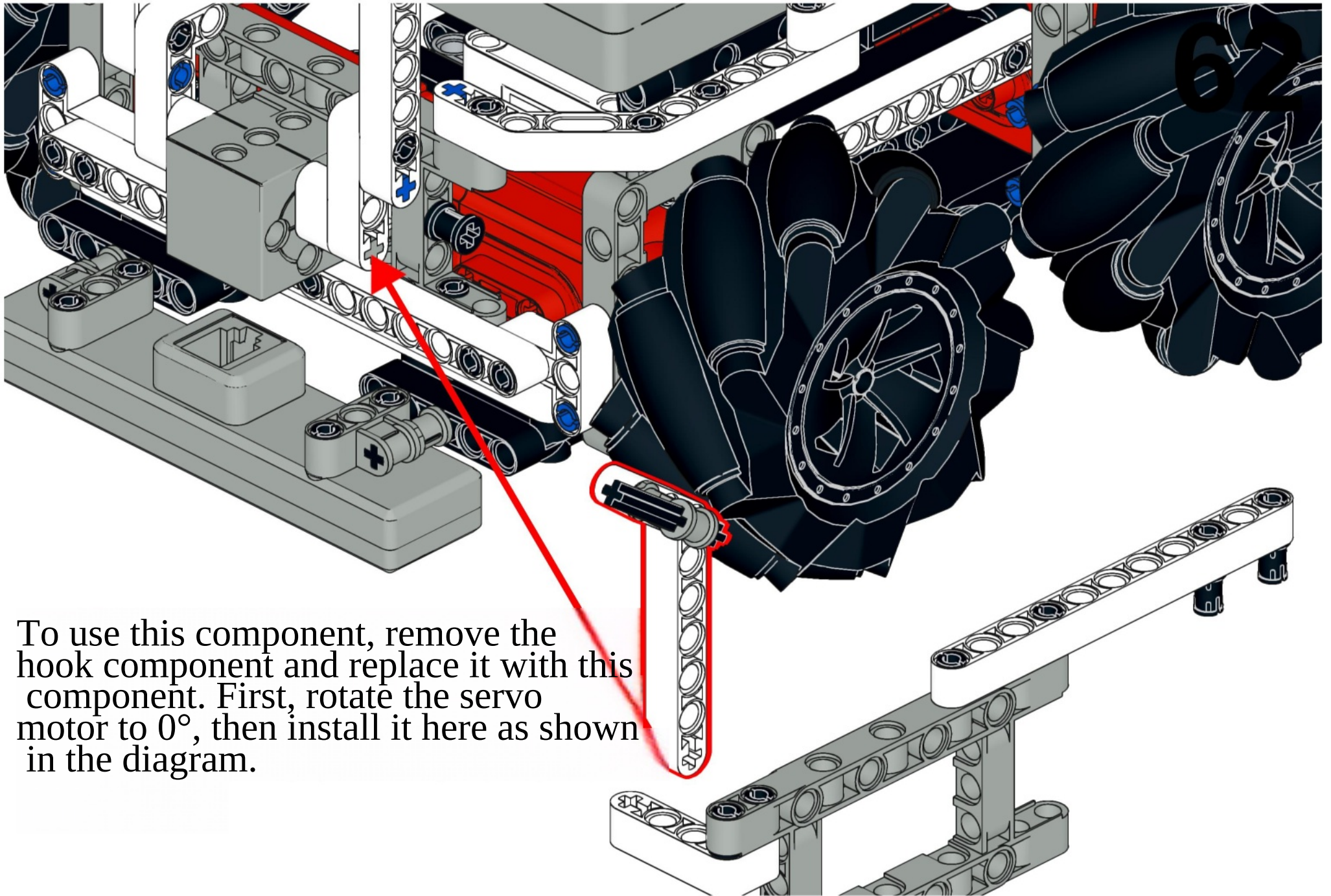




60

61





To use this component, remove the hook component and replace it with this component. First, rotate the servo motor to 0°, then install it here as shown in the diagram.

63

